

User's Manual

Model UP350 Program Controller

User's Manual

Installation

IM 05E01D02-01E

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This manual describes installation, wiring, and other tasks required to make the controller ready for operation.

Contents

1. Safety Precautions
2. Model and Suffix Codes
3. How to Install
4. How to Connect Wires
5. Hardware Specifications
6. Terminal Wiring Diagrams

Introduction

Thank you for purchasing the UP350 program controller. The controller is shipped from the factory with 4 hardcopy user's manuals (A2 size) and 1 user's manual on CD-ROM. The 4 user's manuals in hardcopy format describe the operating procedures required for basic use. It is recommended that you refer to these user's manuals to understand [1] installation, [2] initial settings, [3] program settings, and [4] operating procedures of the controller. The CD-ROM contains an User's Manual (Reference) with descriptions of various functions and setting ranges that can be set as necessary. Moreover, the use of an optional parameter setting tool (model: LL100-E10) allows you to easily perform settings and adjustments with a PC.

How to Use the Manuals

Purpose	Manual Title	Description	Media
Setup	Installation	Describes the tasks (installation, wiring, and others) required to make the controller ready for operations.	A2-size paper, front
Basic operation	Initial Settings	Describes examples of setting PV input types, and control output types. Making settings described herein and program creation in Programming User's Manual allow you to carry out basic control.	A2-size paper, front
Program creation	Programming	Describes examples of creating basic programs. See Program Pattern Setup Charts on the back of Installation User's Manual and program functions.	A2-size paper back and front
Operating procedures and troubleshooting	Operations	Describes key operation sequences. For operation control through external contact inputs, see the back of Installation User's Manual.	A2-size paper, back
Brief operation and setpoint recording	Parameters	Contains the parameter map used as a guideline for setting parameters and lists of parameters for recording User Settings.	A2-size paper, back and front
Detailed description of functions	User's Manual (Reference)	Explains more advanced applications than those found in the 4 hardcopy user's manuals (A2 size).	CD-ROM

1. Safety Precautions

The following symbol is indicated on the controller to ensure safe use.

CAUTION

This symbol on the controller indicates that the operator must refer to an explanation in the user's manual in order to avoid the risk of injury or death of personnel or damage to the instrument. The manual describes how the operator should exercise special care to avoid electric shock or other dangers that may result in injury or loss of life.

The following symbols are used in the hardcopy user's manuals and in the user's manual supplied on the CD-ROM.

NOTE

Indicates that operating the hardware or software in a particular manner may damage it or result in a system failure.

IMPORTANT

Draws attention to information that is essential for understanding the operation and/or features of the controller.

Exemption from Responsibility

Make sure that all of the precautions are strictly adhered to. Yokogawa Electric Corporation assumes no liability for any damage resulting from use of the instrument in contradiction to the precautions. Also, Yokogawa Electric Corporation assumes no liability to any party for any loss or damage, direct or indirect, caused by the use or any unpredictable defect of the instrument. **Regarding Protection, Safety, and Prohibition Against Unauthorized Modification**
(1) In order to protect the product and the system controlled by it against damage and ensure its safe use, make certain that all of the instructions and precautions relating to safety contained in this document are strictly adhered to. Yokogawa does not guarantee safety if products are not handled according to these instructions.
(2) Modification of the product is strictly prohibited.

2. Model and Suffix Codes

Before using the controller, check that the model and suffix codes match your order.

Model	Suffix Code	Description
UP350		Program controller (provided with retransmission output and 15V DC loop power supply as standard)
Type	-0	Standard type
Optional functions	0	None
	1	With communication

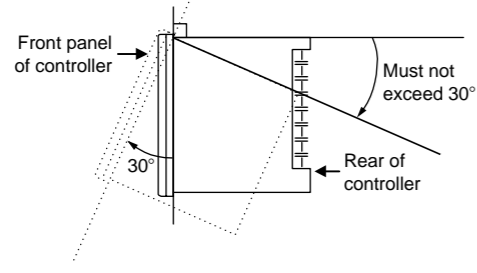
Check that the following items are provided:

- Program controller (of ordered model): 1
- Brackets (mounting hardware): 1 pair
- Unit label: 1
- User's Manuals: 4 (A2 size)
- User's Manual (Reference) (CD-ROM version): 1

3. How to Install

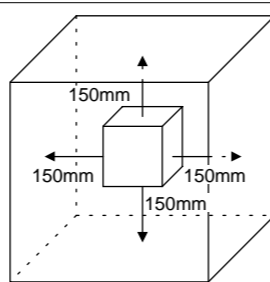
Installation Position

Install the controller at an angle within 30° from horizontal with the front panel facing upward. Do not install it facing downward. The position of right and left sides should be horizontal.



NOTE

- To install the controller, select a location where:
- (1) no one may accidentally touch the terminals,
 - (2) mechanical vibrations are minimal,
 - (3) corrosive gas is minimal,
 - (4) temperature can be maintained at about 23°C and the fluctuation is minimal,
 - (5) no direct radiant heat is present,
 - (6) no magnetic disturbances are caused,
 - (7) no wind blows against the terminal board (reference junction compensation element),
 - (8) no water is splashed,
 - (9) no flammable materials are around.

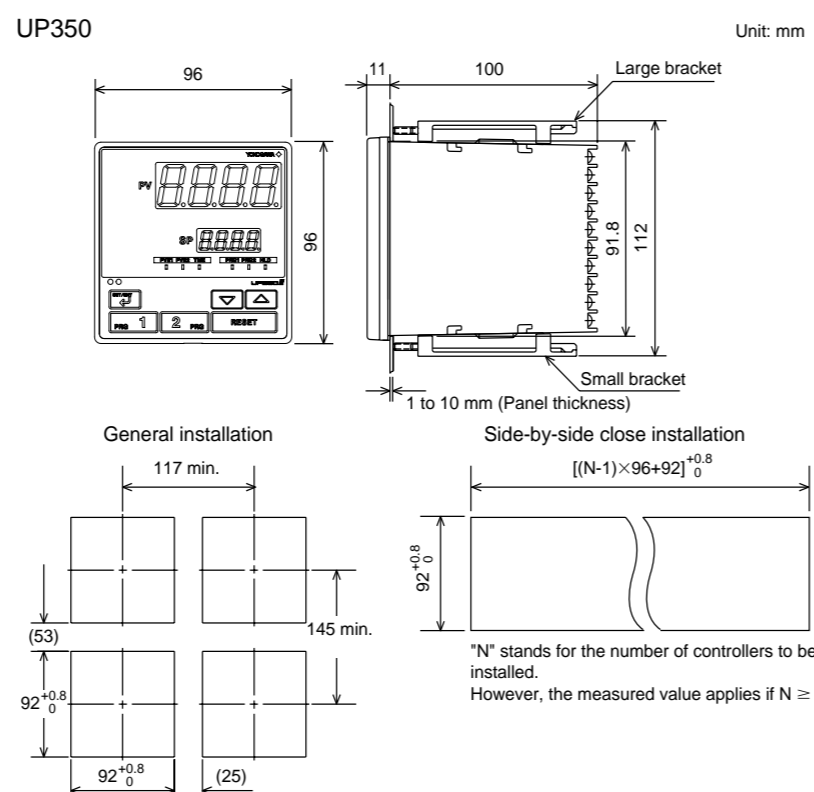


Never place the controller directly on flammable items or equipment. If the controller has to be installed close to flammable items or equipment, be sure to provide shielding panels all around the controller, at least 150mm away from every side; the panels should be made of either 1.43mm-thick metal-plated steel plates or 1.6mm-thick uncoated steel plates.

NOTE

Never touch the opening at the bottom of the case. It is to be used in the factory at shipping.

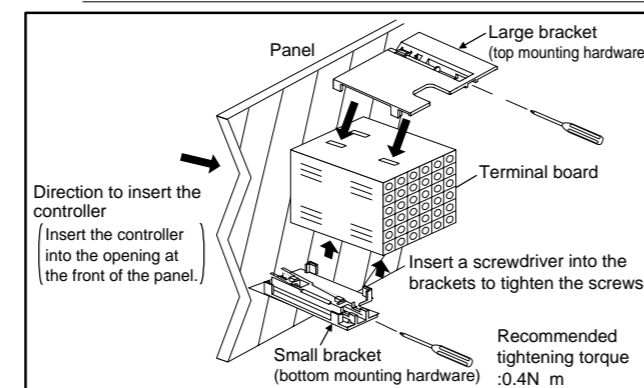
External Dimensions and Panel Cutout Dimensions



How to Install

CAUTION

Turn off the power to the controller before installing it on the panel because there is a possibility of electric shock.



After opening the mounting hole on the panel, follow the procedures below to install the controller:

1. Insert the controller into the opening from the front of the panel so that the terminal board on the rear is at the far side.
2. Set the brackets in place on the top and bottom of the controller as shown in the figure on the left, then tighten the screws of the brackets. Take care not to over-tighten them.

4. How to Connect Wires

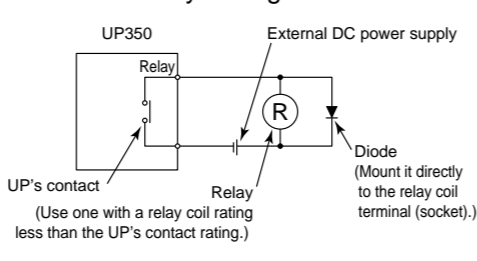
CAUTION

- 1) Before carrying out wiring, turn off the power to the controller and check that the cables to be connected are not alive with a tester or the like because there is a possibility of electric shock.
- 2) For the protection and safe use of the controller, be sure to place a circuit breaker (conforms with IEC60947, 5A, 100V or 220V AC) near the controller where the breaker can easily be operated. In addition, be sure to indicate that it is the instrument to cut the power supply of the controller.
- 3) Wiring must be carried out by personnel who have basic electrical knowledge and practical experience.

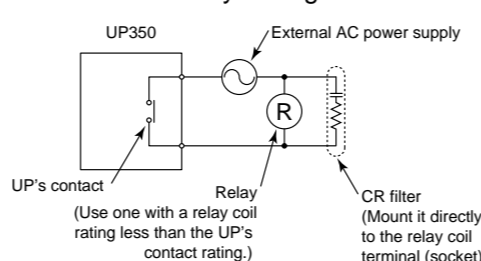
NOTE

- 1) Provide power from a single-phase instrument power supply. If there is a lot of noise in the power line, insert an insulating transformer into the primary side of the line and use a line filter (recommended part: ZAC2205-00U from TDK) on the secondary side. As a countermeasure against noise, do not place the primary and secondary power cables close to each other.
- 2) For thermocouple input, use shielded compensating lead wires for wiring. For RTD input, use shielded wires that have low conductor resistance and cause no significant differences in resistance between the three wires. The cables to be used for wiring, terminal specifications, and recommended parts are as shown below.
- 3) Control output relays may be replaced. However, because they have a life of 100,000 times that of the resistance load, use auxiliary relays to turn on/off a load.
- 4) The use of inductance (L) loads such as auxiliary relays, motors and solenoid valves causes malfunction or relay failure; always insert a CR filter for use with alternating current or a diode for use with direct current, as a spark-removal surge suppression circuit, into the line in parallel with the load.
- 5) When there is possibility of being struck by external lightning surge, use the arrester to protect the instrument.

For DC Relay Wiring



For AC Relay Wiring

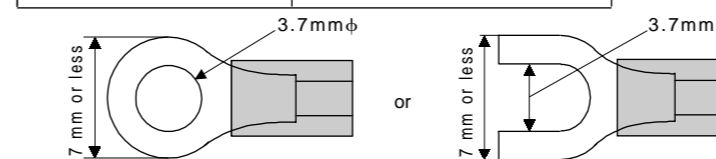


Cable Specifications and Recommended Cables

Purpose	Name and Manufacturer
Power supply, grounding, relay contact outputs	600 V PVC insulated wires, JIS C 3307, 0.9 to 2.0 mm ²
Thermocouple	Shielded compensating lead wires, JIS C 1610, □X-□-□-□-□ (See Yokogawa Electric's GS 6B1U1-E.)
RTD	Shielded wires (three conductors), UL2482 (Hitachi Cable)
Other signals	Shielded wires

Recommended Terminal Lugs

Applicable wire size	Tightening torque
0.3 to 1.65 mm ²	0.8 N·m or less



Terminal Covers (Optional parts)

Target Model	Part Number	Sales Unit
UP350	T9115YD	1

5. Hardware Specifications

PV Input Signals

- Number of inputs: 1 (terminals ①-③)
- Input type: Universal input system. The input type can be selected with the software.
- Sampling period: 250 ms
- Burnout detection: Functions at TC, RTD, standard signal (0.4 to 2 V or 1 to 5 V)
Upscale, downscale, and off can be specified. For standard signal, burnout is determined to have occurred if it is 0.1 V or less.
- Input bias current: 0.05 μA (for TC or RTD b-terminal)
- Measurement current (RTD): About 0.13 mA
- Input resistance: 1 MΩ or more for thermocouple or mV input
- Allowable signal source resistance: 250 Ω or less for thermocouple or mV input
Effects of signal source resistance: 0.1 μV/Ω or less 2 kΩ or less for DC voltage input
Effects of signal source resistance: About 0.01%/100 Ω
- Allowable wiring resistance: for RTD input
Maximum 150 Ω/wire: Conductor resistance between three wires should be equal
However, 10 Ω/wire for a maximum range of -150.0 to 150.0°C.
Wire resistance effect: ±0.1°C /10 Ω
- Allowable input voltage: ±10 V DC for thermocouple, mV, or RTD input
±20 V DC for DC voltage input
- Noise rejection ratio: 40 dB (50/60 Hz) or more in normal mode 120 dB (50/60 Hz) or more in common mode
- Reference junction compensation error: ±1.0°C (15 to 35°C) ±1.5°C (0 to 15°C, 35 to 50°C)
- Applicable standards: JIS, IEC, DIN (ITS-90) for thermocouples and RTD

Control Output

Universal output system. The output type can be selected with the software.

- Current output (Standard type: terminals ⑥-⑩)

Number of outputs	1 (switched between a voltage pulse output and current output)
Output signal	4-20 mA DC
Load resistance	600 Ω or less
Output accuracy	±0.3% of span under standard operating conditions (23 ± 2 °C, 55 ± 10% RH, power frequency of 50/60 Hz)
Resolution	10 ms

- Voltage pulse output (Standard type: terminals ⑥-⑩)

Number of outputs	1 (switched between a voltage pulse output and current output)
Output signal	On-voltage = 12 V or more (load resistance: 600 Ω or more) Off-voltage = 0.1 V DC or less
Resolution	10 ms

- Relay contact output (Standard type: terminals ①-③, ③)

Number of outputs	1
Output signal	Three terminals (NC, NO, and common)
Contact rating	250 V AC or 30 V DC, 3 A (resistance load)
Resolution	10 ms

Contact Inputs

- Purpose: Run/Reset switching
- Number of inputs: 2 points
- Input type: Non-voltage contact or transistor open collector input
- Input contact rating: 12 V DC, 10 mA or more
- On/off determination: For non-voltage contact input, contact resistance of 1 kΩ or less is determined as "on" and contact resistance of 20 kΩ or more as "off."
For transistor open collector input, input voltage of 2 V or less is determined as "on" and leakage current must not exceed 100 μA when "off."
- Minimum status detection hold time: About 1 second

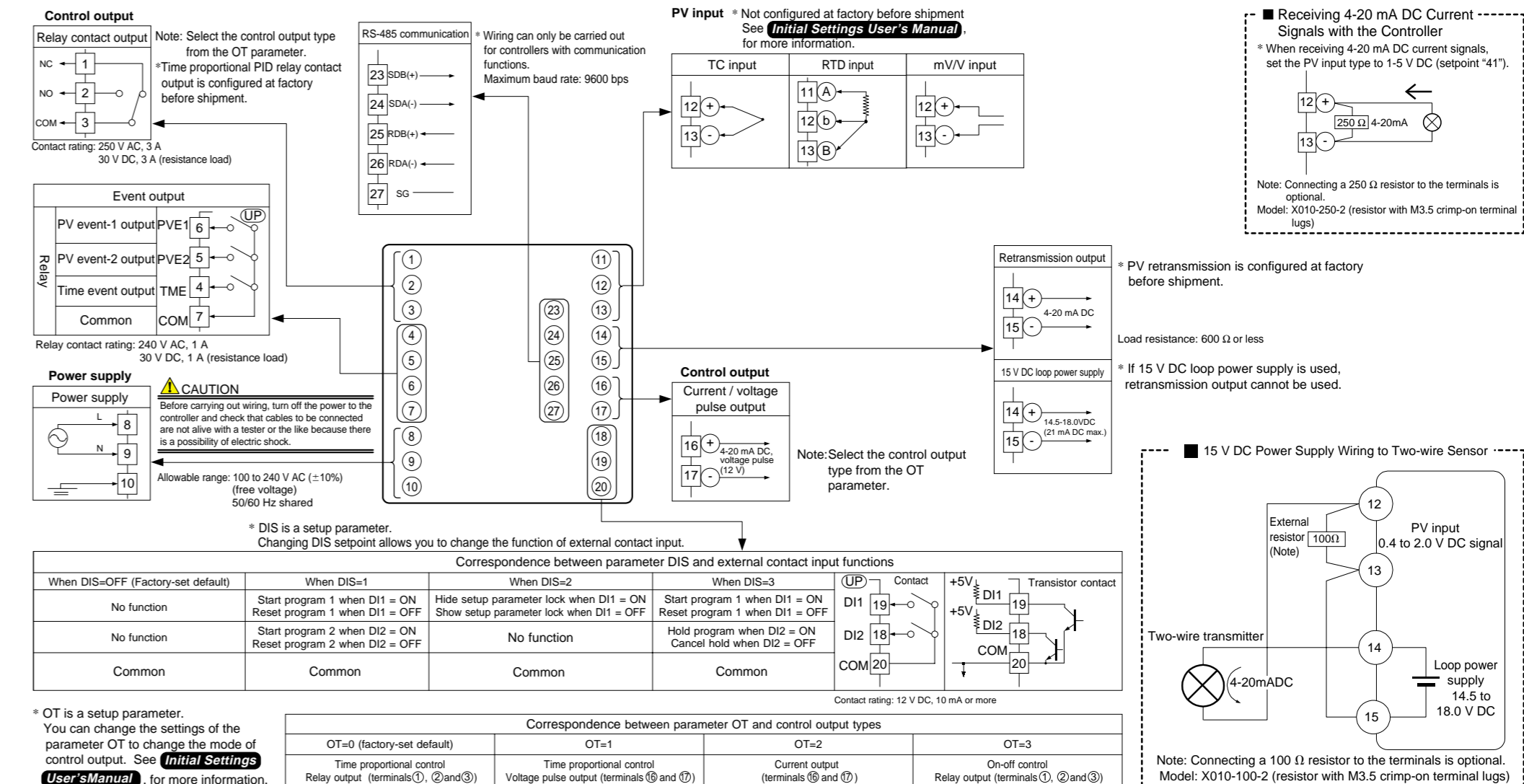
Retransmission Output

Either PV, program setpoint, or control output is output. Either the retransmission output or the loop power supply can be used with terminals ③-⑤.

6. Terminal Wiring Diagrams

Do not use unassigned terminals as relay terminals.

UP350 Standard Type (Model UP350-0□)



Contact Outputs

- Purpose: PV event outputs (2) and time event output (1)
- Number of outputs: 3 points
- Relay contact rating: 240 V AC, 1 A, or 30 V DC, 1 A

Display Specifications

- PV display: 4-digit, 7-segment red LED display, character height of 20 mm
- Setpoint display: 4-digit, 7-segment red LED display character height of 9.3 mm
- Status indicating lamps: LEDs

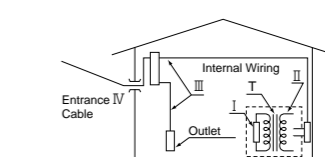
Safety and EMC Standards

- Safety: Compliant with IEC/EN61010-1: 2001, approved by CSA1010, approved by UL508.
Installation category : CAT. II (IEC/EN61010, CSA1010)
Pollution degree : 2 (IEC/EN61010, CSA1010)
Measurement category : 1 (CAT. I : IEC/EN61010)
Rated measurement input voltage : 10V DC max.(across terminals), 300V AC max.(across ground)
Rated transient overvoltage : 1500V (Note)
Note : It is a value on the safety standard which is assumed by IEC/EN61010-1 in measurement category I, and is not the value which guarantees an apparatus performance.

CAUTION

This equipment has Measurement category I, therefore do not use the equipment for measurements within measurement categories II, III and IV.

Measurement category	Description	Remarks
I	CAT. I For measurements performed on circuits not directly connected to Mains	
II	CAT. II For measurements performed on circuits directly connected to the low voltage installation	Appliances, portable equipments, etc.
III	CAT. III For measurements performed in the building installation	Distribution board, circuit breaker, etc.
IV	CAT. IV For measurements performed at the source of the low-voltage installation	Overhead wire, cable systems, etc.



- EMC standards: Complies with EN61326.

The instrument continues to operate at a measuring accuracy of within ±20% of the range during tests.

Construction, Installation, and Wiring

- Construction: Only the front panel is dust-proof and drip-proof (protection class IP55)
For side-by-side close installation the controller loses its dust-proof and drip-proof protection.
- Material: ABS resin and polycarbonate
- Case color: Black
- Weight: About 1 kg or less
- Dimensions: 96 (W) × 96 (H) × 100 (depth from panel face) mm
- Installation: Panel-mounting type. With top and bottom mounting hardware (1 each)
- Panel cutout dimensions: 92^{+0.8} (W) × 92^{+0.8} (H) mm
- Installation position: Up to 30° upward facing (not designed for facing downward)
- Wiring: M3.5 screw terminals (for signal wiring and power/ground wiring as well)

Power Supply Specifications

- Power supply: Rated voltage of 100 to 240 V AC (±10%), 50/60 Hz
- Power consumption: Max. 20 VA (8.0 W max.)
- Internal fuse rating: 250 V AC, 1.6A time-lag fuse
- Data backup: Non-volatile memory (can be written to up to 100,000 times)

- Withstanding voltage
 - Between primary terminals* and secondary terminals**:
 - At least 1500 V AC for 1 minute
 - Between primary terminals* and grounding terminal:
 - At least 1500 V AC for 1 minute
 - Between grounding terminal and secondary terminals**:
 - At least 1500 V AC for 1 minute
 - Between secondary terminals**:
 - At least 500 V AC for 1 minute
- * Primary terminals indicate power terminals and relay output terminals
- ** Secondary terminals indicate analog I/O signal, voltage pulse output, and contact input terminals
- Insulation resistance: 20 MΩ or more at 500 V DC between power terminals and grounding terminal
- Grounding resistance: Class 3 grounding (grounding resistance of 100 Ω or less)

Signal Isolations

- PV input terminals: Isolated from other input/output terminals. Not isolated from the internal circuit.
- 15 V DC loop power supply terminals: Not isolated from 4-20 mA analog output and voltage pulse control output. Isolated from other input/output terminals and internal circuit.
- 4-20 mA analog output terminals (for control output and retransmission): Not isolated between 4-20 mA outputs and from 15 V DC loop power supply and voltage pulse control output. Isolated from other input/output terminals and internal circuit.
- Voltage pulse control output terminals: Not isolated from 4-20 mA outputs and 15 V DC loop power supply. Isolated from other input/output terminals and internal circuit.
- Relay contact control output terminals: Isolated between contact output terminals and from other input/output terminals and internal circuit.
- Contact input terminals: Not isolated between contact input terminals and from communication terminals. Isolated from other input/output terminals and internal circuit.
- Relay contact event output terminal: Not isolated from each other; isolated from other input/output terminals and the internal circuit.
- RS-485 communication terminals: Not isolated from contact input terminals. Isolated from other input/output terminals and internal circuit.
- Power terminals: Isolated from other input/output terminals and internal circuit.
- Grounding terminals: Isolated from other input/output terminals and internal circuit.

Environmental Conditions

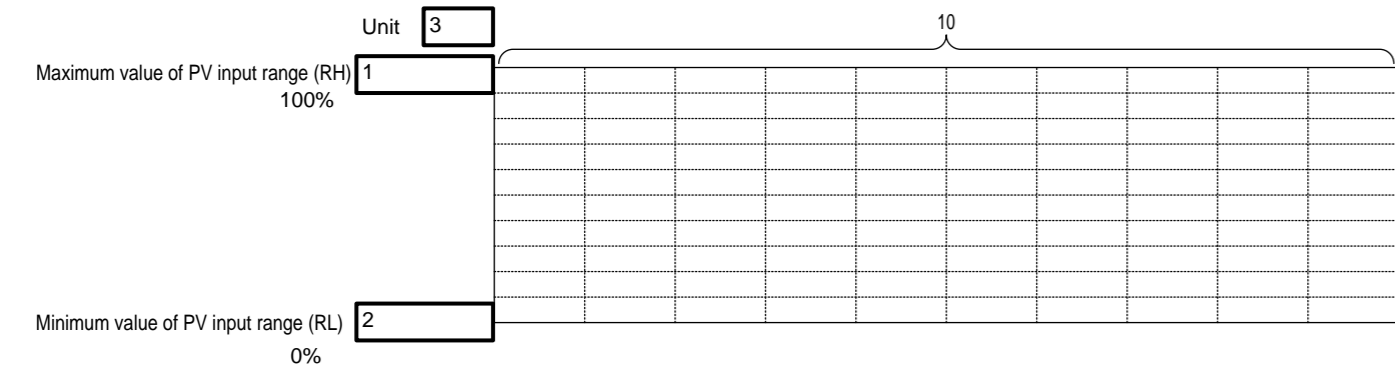
- Normal operating conditions:
 - Ambient temperature: 0 to 50°C (40°C or less for side-by-side close installation)
 - Temperature change rate: 10°C/h or less
 - Ambient humidity: 20 to 90% RH (no condensation allowed)
 - Magnetic field: 400 A/m or less
 - Continuous vibration at 5 to 14 Hz: Full amplitude of 1.2 mm or less
 - Continuous vibration at 14 to 150 Hz: 4.9 mm/s² or less
 - Short-period vibration: 14.7 m/s², 15 seconds or less
 - Shock: 147 m/s² or less, 11 ms
 - Installation height: Height above sea level of 2000 m or less
 - Warm-up time: 30 minutes or more after power on
- Transportation and storage conditions:
 - Temperature: -25 to 70°C
 - Temperature change rate: 20°C/h or less
 - Humidity: 5 to 95% RH (no condensation allowed)
- Effects of changes in operating conditions
 - Effects from changes in ambient temperature:
 - On voltage or thermocouple input, ±1 μV/°C or ±0.01% of F.S./°C, whichever is larger
 - On RTD input, ±0.05°C/°C (ambient temperature) or less
 - On analog output, ±0.05% of F.S./°C or less
 - Effects from power supply fluctuation (within rated voltage range):
 - On analog input, ±1 μV/V or ±0.01% of F.S./10 V, whichever is larger
 - On analog output, ±0.05% of F.S./10 V or less

Program Pattern Setup Charts

See "1. Overview of Program Patterns" and "2. Example of Program Pattern Setup Charts" in the **Programming User's Manual** for details on how to use the setting charts. There are two identical charts shown below because two programs can be registered with the UP350. Fill in the fields with bold-face borders in the order of steps 1 to 10, as shown below. Then, input these setup data items to the UP350.

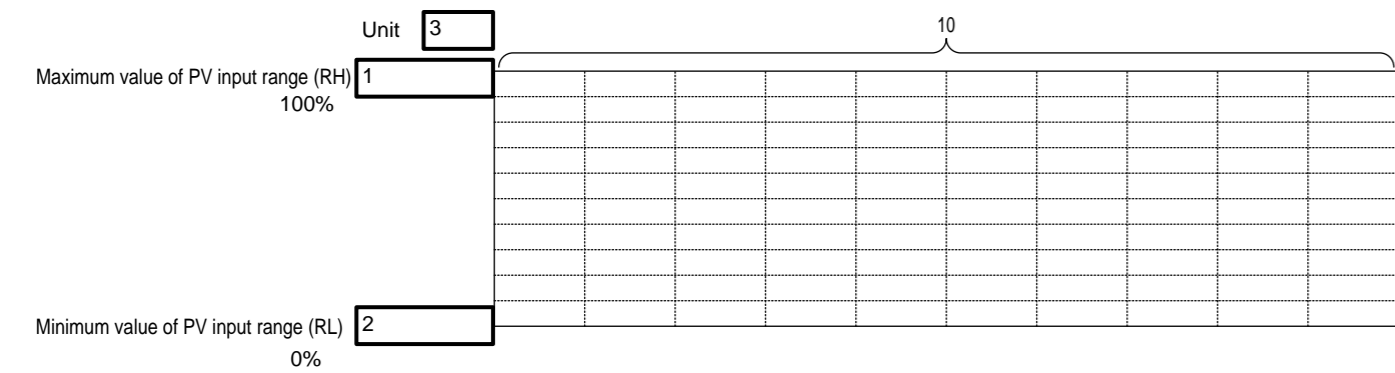
1. Maximum value of PV input range: Setpoint of the setup parameter "Maximum Value of PV Input Range (RH)"
2. Minimum value of PV input range: Setpoint of the setup parameter "Minimum Value of PV Input Range (RL)"
3. PV input unit: Setpoint of the setup parameter "PV Input Unit (UNIT)"
4. Program time unit: Setpoint of the setup parameter "Program Time Unit (TMU)"
5. Segment setting method: Setpoint of the setup parameter "Segment Setting Method (SEG.T)"
6. Starting target setpoint: Setpoint of the program parameter "Starting Target Setpoint (SSP)"
7. Start code: Setpoint of the program parameter "Start Code (STC)"
8. Junction code: Setpoint of the program parameter "Junction Code (JC)"
9. Target setpoint, Segment time, PV events 1 and 2, and Time event: Setpoint of each program parameter
10. Draw the program pattern.

System name		Program time unit (TMU)	4	Starting target setpoint (SSP)	6
Program No.		Segment setting method (SEG.T)	5	Start code (STC)	7
Program name				Junction code (JC)	8
Model	UP350 -				
Serial No.					



Segment No.		1	2	3	4	5	6	7	8	9	10
Target setpoint (SP)											
Segment time (TM)											
PV event 1	Event type (AL1)										
	Event setpoint (A1)										
PV event 2	Event type (AL2)										
	Event setpoint (A2)										
Time event	On time of time event (EON)										
	Off time of time event (EOF)										

System name		Program time unit (TMU)	4	Starting target setpoint (SSP)	6
Program No.		Segment setting method (SEG.T)	5	Start code (STC)	7
Program name				Junction code (JC)	8
Model	UP350 -				
Serial No.					



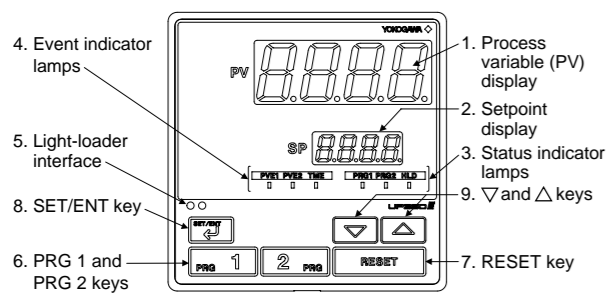
Segment No.		1	2	3	4	5	6	7	8	9	10
Target setpoint (SP)											
Segment time (TM)											
PV event 1	Event type (AL1)										
	Event setpoint (A1)										
PV event 2	Event type (AL2)										
	Event setpoint (A2)										
Time event	On time of time event(EON)										
	Off time of time event(EOF)										

This manual describes examples of setting PV input types, and control output types. Carrying out settings described herein allows you to perform basic control. Refer to examples of various settings to understand how to set parameters required. Refer to "1. Parameter Map" in **Parameters User's Manual** for an easy to understand explanation of setting various parameters. If you cannot remember how to carry out an operation during setting, press the key for more than 3 seconds. This brings you to the display (operating display) that appears at power-on. When you have finished configuring the initial settings discussed in this manual, create operation programs as explained in **Programming User's Manual**.

Contents

- Names and Functions of Front Panel Parts
- Setting PV Input Type (Setting First at Power-on)
- Changing PV Input Type
- Setting Control Output Type

1. Names and Functions of Front Panel Parts



Name of Part	Function
1. Process variable (PV) display	<ul style="list-style-type: none"> Displays PV during operation. Displays a parameter symbol when you set a parameter. Displays an error code in red if the controller fails.
2. Setpoint display	<ul style="list-style-type: none"> Displays such data items as the program setpoint and control output value (OUT), as shown below, during operation. Program setpoint Segment number for which operation is in progress Remaining segment time Program setpoint at the time of hold (shown when program operation is at a pause) Control output value Displays the setpoint of a parameter when it is configured.
3. Status indicator lamps	<ul style="list-style-type: none"> Remain lit during operation. PRG1: Program-1 operation PRG2: Program-2 operation HLD: Hold operation (lit when program operation is paused)
4. Event indicator lamps	<ul style="list-style-type: none"> Come on when PV event 1 or 2, or a time event occurs. PVE1: PV event 1 PVE2: PV event 2 TIME: Time event
5. Light-loader interface	<ul style="list-style-type: none"> A communication interface for connection with an adapter cable when setting and storing parameters from a PC. Use of this interface requires an optional parameter setting tool. Used to start program operation or set a program. Operation with program pattern 1: With the operating display shown, hold down the PRG1 key for more than 2 seconds. Operation with program pattern 2: With the operating display shown, hold down the PRG2 key for more than 2 seconds.
6. PRG1 and PRG2 keys	<ul style="list-style-type: none"> Setting of program pattern 1: With the operating parameter setting display shown, press the PRG1 key to show the relevant program setting parameter. Setting of program pattern 2: With the operating parameter setting display shown, press the PRG2 key to show the relevant program setting parameter.
7. RESET key	<ul style="list-style-type: none"> Press this key for more than 2 seconds during normal operation or hold operation to stop the operation. When stopped, the controller outputs a fixed value (preset output value). The output is factory-set to 0.0% or OFF.
8. SET/ENT key	<ul style="list-style-type: none"> Used to switch or register parameters. Press this key for more than 3 seconds to alternate between the operating display and the menu for operating parameter setting display.
9. and keys	<ul style="list-style-type: none"> Used to change numerical values. On setting displays for various parameters, you can change the program setpoints, and parameters values. Pressing the key increases a numerical value, while pressing the key causes it to decrease. You can hold down either key to gradually increase the speed of change.

IMPORTANT

The controller automatically returns to the display at the time of power-on (i.e., operating display) if no key is operated for at least one minute.

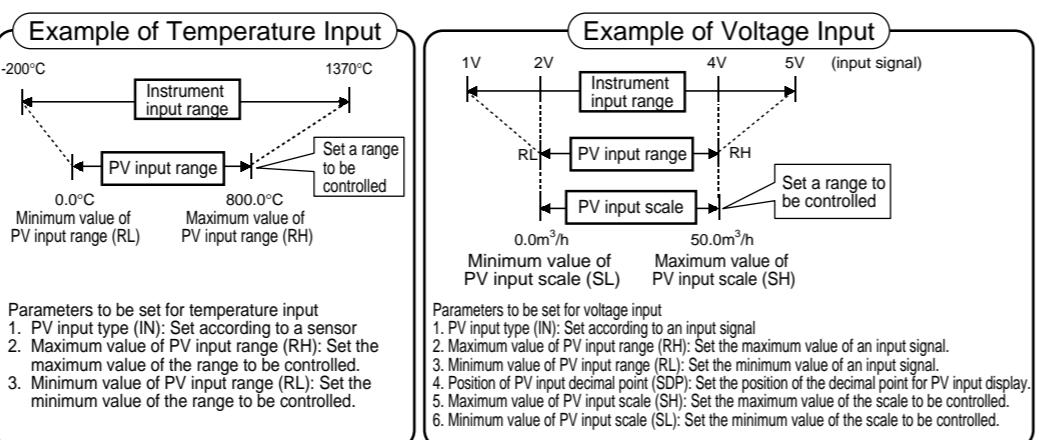
Factory-set Values of Main Parameters

Item	Factory-set default of standard type controller
Control output	Time proportional PID relay output (variable)
Control action	Reverse action (variable)
PID parameters	P = 5.0%, I = 240 seconds, D = 60 seconds

2. Setting PV Input Type (Setting First at Power-on)

NOTE

- The controller displays the operating display when the power is turned on. However, if PV input type has not been set, "IN" appears. In this case, first use the key to display the input range code to use, then press the key to register it. Then, set the maximum value (RH) and minimum value (RL) of the PV input range (for voltage input, set the maximum value (SH) and minimum value (SL) of the PV input scale).
- The controller is configured to the initial value of each parameter at the factory before shipment. First check the initial values shown in 2. Lists of Parameters, in **Parameters User's Manual** and change parameter values as necessary.



The following operating procedure describes an example of setting a K-type thermocouple (-199.9°C to 500.0°C) and a measurement range of 0.0°C to 200.0°C.

- Display screen at power-on. The parameter "IN" for setting the PV input type appears. Displays parameter "IN".
- Press the or key to display the required setpoint. The figure below is an example of the controller setting a K-type thermocouple (-199.9 to 500.0°C). See "Instrument Input Range Codes." Displays parameter "RH".
- Press the key once to register the required setpoint. Blinks during change.
- Press the key once to display the parameter "UNIT" (PV input unit). Displays parameter "UNIT".
- Press the key once to display the parameter "RH" (maximum value of PV input range). Displays parameter "RH".
- Press the or key to display the required setpoint. The figure below shows an example of setting the maximum value of PV input range to 200.0°C. Blinks during change.
- Press the key once to register the setpoint. Displays parameter "RH".
- Press the or key to display the required setpoint. The figure below shows an example of setting the minimum value of PV input range to 0.0°C. Blinks during change.
- Press the key once to register the setpoint. Displays parameter "RL".
- Press the or key to display the required setpoint. The figure below shows an example of setting the minimum value of PV input range to 0.0°C. Blinks during change.
- Press the key once to display the parameter "UNIT" (PV input unit). Displays parameter "UNIT".
- Press the key once to register the setpoint. Blinks during change.
- To set the type of control output, see steps 7 and later in "4 Setting Control Output Type." To finish settings, press the key for more than 3 seconds. This returns you to the display shown at power-on (figure below). Displays PV.
- Press the or key to display the required setpoint. The figure below shows the error code for input burnout (b00b) if PV input wiring is not yet complete. The error code disappears when you wire the PV input terminals correctly. Displays PV.

Instrument Input Range Codes

Input	Type	Instrument Input Range Code	Instrument Input Range	Measurement Accuracy
Unspecified		OFF	Set the data item PV Input Type "IN" to the OFF option to leave the PV input type undefined.	
K		1	-200 to 1370°C -300 to 2500°F	±0.1% of instrument range ±1 digit for temperatures equal to or higher than 0°C ±0.2% of instrument range ±1 digit for temperatures below 0°C
		2	-199.9 to 999.9°C 0 to 2300°F	
		3	-199.9 to 500.0°C -199.9 to 999.9°F	
		4	-199.9 to 999.9°C -300 to 2300°F	
		5	-199.9 to 400.0°C -300 to 750°F	
		6	0.0 to 400.0°C -199.9 to 750.0°F	
Thermocouple		7	0 to 1800°C 32 to 3300°F	±0.15% of instrument range ±1 digit for temperatures equal to or higher than 400°C ±5% of instrument range ±1 digit for temperatures below 400°C
		8	0 to 1700°C 32 to 3100°F	
		9	0 to 1700°C 32 to 3100°F	
		10	-200 to 1300°C -300 to 2400°F	
		11	-199.9 to 999.9°C -300 to 1800°F	
		12	-199.9 to 900.0°C -300 to 1300°F	
RTD		13	-199.9 to 400.0°C -300 to 750°F	±0.1% of instrument range ±1 digit for temperatures equal to or higher than 0°C ±0.2% of instrument range ±1 digit for temperatures below 0°C
		14	0.0 to 400.0°C -199.9 to 750.0°F	
		15	0 to 2300°C 32 to 4200°F	
		16	0 to 1390°C 32 to 2500°F	
		17	0 to 1900°C 32 to 3400°F	
		18	0 to 2000°C 32 to 3600°F	
Standard signal		30	-199.9 to 500.0°C -199.9 to 999.9°F	±0.1% of instrument range ±1 digit (Note1) (Note2)
		31	-150.0 to 150.0°C -199.9 to 300.0°F	
		35	-199.9 to 850.0°C -300 to 1560°F	
		36	-199.9 to 500.0°C -199.9 to 999.9°F	
		37	-150.0 to 150.0°C -199.9 to 300.0°F	
		40	0.400 to 2.000 V	
41	1.000 to 5.000 V			
50	0.000 to 2.000 V			
51	0.00 to 10.00 V			
55	-10.00 to 20.00 mV			
56	0.0 to 100.0 mV			
DC voltage		40	0.400 to 2.000 V	±0.1% of instrument range ±1 digit (Note) The read-out range can be scaled between -1999 and 9999.
		41	1.000 to 5.000 V	
		50	0.000 to 2.000 V	
		51	0.00 to 10.00 V	
		55	-10.00 to 20.00 mV	
		56	0.0 to 100.0 mV	

* Performance in the standard operating condition (at 23±2°C, 55±10%RH, and 50/60 Hz power frequency)
 Note1: The accuracy is ±0.3°C of instrument range ±1 digit for a temperature range from 0°C to 100°C.
 Note2: The accuracy is ±0.5°C of instrument range ±1 digit for a temperature range from -100°C to 200°C.
 * To receive a 4-20 mA DC signal, select a standard signal of 1 to 5 V DC and connect it to a 250Ω resistor. This resistor is optional.
 Model: X010-250-2 (resistor with M3.5 crimp-on terminal lugs)

NOTE

The controller may automatically initialize the registered operating parameter setpoints if any change is made to the data item PV Input Type (IN), Maximum Value of PV Input Range (RH), Minimum Value of PV Input Range (RL), PV Input Decimal Point Position (SDP), Maximum Value of PV Input Scale (SH) or Minimum Value of PV Input Scale (SL). After a change has been made to any of these data items, be sure to verify the registered operating parameter setpoints to ensure that they are correct. If any data item has been changed to its default, set it to a required value.

3. Changing PV Input Type

The following operating procedure describes an example of changing the setting of K-type thermocouple (-199.9 to 500.0°C) to RTD Pt100 (-199.9 to 500.0°C) and a measurement range of 0.0 to 200.0°C.

- Bring the operating display into view (display appears at power on). Displays PV.
- Press the key for more than 3 seconds to call up the menu "OP.PA". Displays menu "OP.PA".
- Press the key once to display the menu "STUP". Displays menu "STUP".
- Press the key once to display the parameter "PWD". Displays menu "PWD".
- Press the key once to display the menu "FUNC". Displays menu "FUNC".
- Press the key once to display the menu "I/O". Displays menu "I/O".
- Press the key once to display the parameter "STUP". Displays menu "STUP".
- Press the key once to display the parameter "IN" (PV input type). Displays parameter "IN".
- Press the or key to display the required setpoint. The figure below shows an example of changing to RTD Pt100 (-199.9 to 500.0°C). Blinks during change.

- Press the key once to register the setpoint. Displays parameter "RL".
- Press the key once to display the parameter "UNIT" (PV input unit). Displays parameter "UNIT".
- Press the key once to display the parameter "RH" (maximum value of PV input range). Displays parameter "RH".
- Press the or key to display the required setpoint. The figure below shows an example of setting the minimum value of PV input range to 0.0°C. Blinks during change.
- Press the key once to register the setpoint. Displays parameter "RH".
- Press the key for more than 3 seconds. This returns you to the display shown at power-on (figure below). Displays PV.
- Press the key once to register the setpoint. * If the type of input is voltage, also configure the PV Input Decimal Point Position (SDP), Maximum Value of PV Input Scale (SH) and Minimum Value of PV Input Scale (SL) parameters that are displayed after parameter RL. Displays parameter "RH".

4. Setting Control Output Type

The following operating procedure describes an example of changing time proportional PID relay output (0/on-off(3) output) to current output (2).
 Control output terminal Values in parentheses are setpoints
 Time proportional PID relay (0)/on-off(3) output..... ①-②-③
 Current (2)/time proportional PID voltage pulse (1) output..... ④-⑤

- Bring the operating display into view (display appears at power-on). Displays PV.
- Press the key for more than 3 seconds to call up the menu "OP.PA". Displays menu "OP.PA".
- Press the key once to display the menu "STUP". Displays menu "STUP".
- Press the key once to display the parameter "PWD". Displays menu "PWD".
- Press the key once to display the menu "FUNC". Displays menu "FUNC".
- Press the key once to display the menu "I/O". Displays menu "I/O".
- Press the key several times to display the parameter "OT" (control output type). Displays parameter "OT".
- Press the or key to display the required setpoint. The figure below shows an example of setting to current output (4 to 20 mA DC). Blinks during change.
- Press the key once to register the setpoint. Displays parameter "OT".
- Press the key once to display the menu "FUNC". Displays menu "FUNC".
- Press the key for more than 3 seconds. This returns you to the display shown at power-on (figure below). Displays PV.

List of Control Output Types

Parameter Symbol	Parameter Name	Setpoint	Control Output Type
	Control output type	0	Time proportional PID relay contact output (terminals ①-②-③)
		1	Time proportional PID voltage pulse output (terminals ④-⑤)
		2	Current output (terminals ⑥-⑦)
		3	On-off control relay contact output (terminals ①-②-③)

This manual describes key entries for operating the controller. For operations using external contact inputs, see "6. Terminal Wiring Diagrams," in **Installation User's Manual**. If you cannot remember how to carry out an operation during setting, press the **RESET** key for more than 3 seconds. This brings you to the display (operating display) that appears at power-on.

Contents

1. Performing/Canceling Auto-tuning
2. Setting PID Manually
3. Starting (PRG)/Stopping (RESET) the Controller
4. Enabling/Disabling Hold Mode of Program Operation
5. Changing Program Setpoints when in Hold Mode
6. Executing "Advance" Function
7. Troubleshooting

NOTE

Do not use the instrument generating strong magnetic field such as radio equipment and the like near the controller. This may cause the fluctuation of the PV value.

1. Performing/Canceling Auto-tuning

Perform auto-tuning when you have finished creating program patterns. Make sure the controller is in Run state (PRG) before carrying out auto-tuning. See "3. Starting (PRG)/Stopping (RESET) the Controller," to change to PRG. PID constants are obtained by using the current program setpoint value at the start of auto-tuning.

NOTE

When on-off control is being used, auto-tuning cannot be carried out. Moreover, do not perform auto-tuning when controlling any of the following processes.

- Control processes with quick response such as flow control or pressure control
- Processes where even temporary output on/off results in inconvenience
- Processes where a large output change at control element results in inconvenience
- Processes where variations in PV may exceed an allowable range, adversely affecting product quality

- Bring the operating display into view (display appears at power on).
- Press the **RESET** key for more than 3 seconds to call up the menu "OP.PA".
- Press the **RESET** key several times to display the parameter "AT".
- Press the **ENTER** key to display the required setpoint. Set as "AT = 1" to perform auto-tuning for the first group of PID constants.
- Press the **ENTER** key once to register the setpoint. (This starts auto-tuning.)
- During auto-tuning, the panel indications become as shown below.

To cancel auto-tuning, set AT = OFF.

Auto-tuning is complete when the PRG2 lamp goes out.

2. Setting PID Manually

If you know the values to be set or if suitable PID constants cannot be obtained by auto-tuning, follow the procedure below to set values.

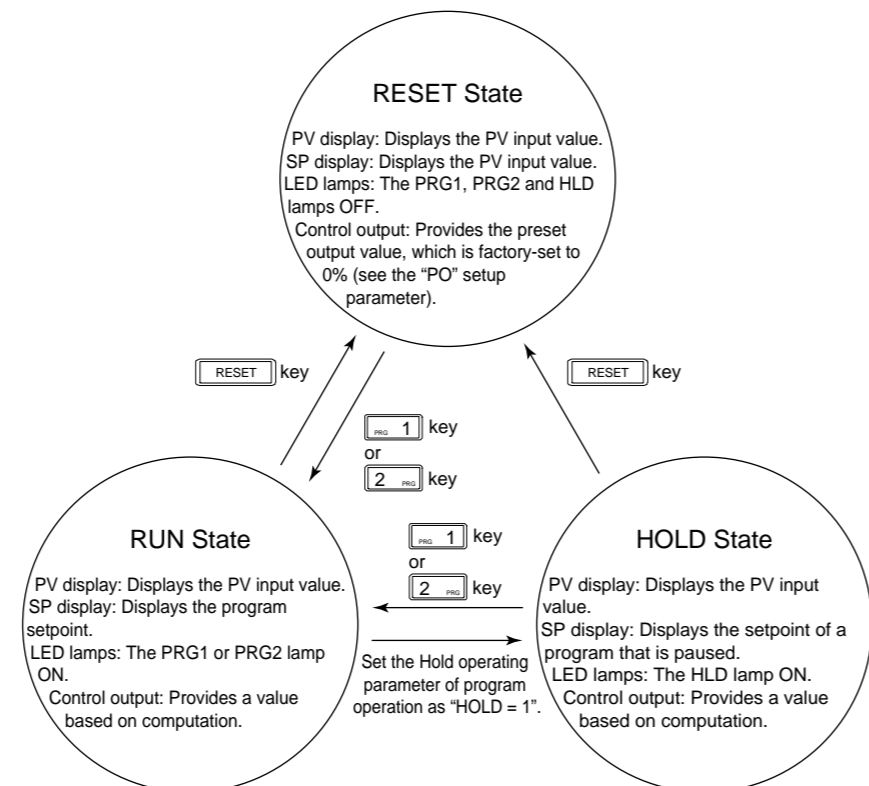
- Bring the operating display into view (display appears at power on).
- Press the **RESET** key for more than 3 seconds to call up the menu "OP.PA".
- Press the **RESET** key several times to display the parameter "PID".
- Press the **ENTER** key once to display "1Gr."
- Press the **ENTER** key once to register the setpoints.
- Press the **ENTER** key once to display the parameter "1.P".

- Press the **ENTER** or **RESET** key to display the required setpoint.
- Press the **ENTER** key once to register the setpoint.
- Press the **ENTER** key for more than 3 seconds. This returns you to the display shown at power-on (figure below).

The same steps can be used for integral time (1.I) and derivative time (1.D) that are displayed after this.

[TIP]
The PID parameter numbers set in step 4. should be set as follows:
In case of PID group 1, PID = 1Gr
In case of PID group 2, PID = 2Gr
In case of PID group 3, PID = 3Gr
In case of PID group 4, PID = 4Gr

Diagram of Operating State Transition



3. Starting (PRG)/Stopping (RESET) the Controller

The following operating procedure starts program operation.

- Bring the operating display into view (appears at power-on).
- Press the **1** key for more than 2 seconds to start program pattern 1.
- Press the **2** key for more than 2 seconds to start program pattern 2.
- To stop program operation, press the **RESET** key for more than 2 seconds.

When in the RESET state, the controller provides the following input/output values.

PV input	Value of process variable
Control output	Preset output value (factory-set to 0%)
Event output	OFF

4. Enabling/Disabling Hold Mode of Program Operation

The following operating procedure brings program pattern 1 into a pause during operation. This procedure also applies to program pattern 2.

NOTE

If a contact input is on (hold mode is set) when the hold mode is enabled and disabled with the input, the mode cannot be cancelled by key operation.

- Bring the operating display into view (appears at power-on).
- Press the **RESET** key for more than 3 seconds to call up the menu "OP.PA".
- Press the **RESET** key three times to display the parameter "HOLD".
- Press the **ENTER** key once to display "1".
- Press the **ENTER** key once to register the setpoint. The HLD lamp ON and the controller under program operation comes to a pause.

To cancel the hold mode, set as "HOLD = 0".

The controller automatically returns to the display shown at power-on (figure below).

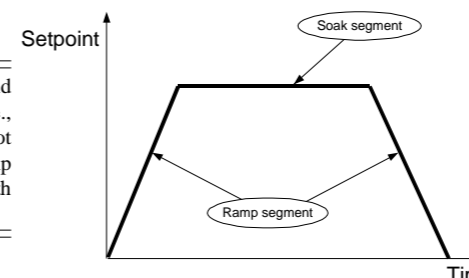
If you have cancelled the hold mode, press the **RESET** key for more than 3 seconds to return to the display shown at power-on.

5. Changing Program Setpoints when in Hold Mode

The following operating procedure changes program setpoints when program operation is put in hold mode. Before changing program setpoints, enable the hold mode of program operation as instructed in "4. Enabling/Disabling the Hold Mode of Program Operation." When you have finished changing the setpoints, cancel the hold mode. The controller continues program operation using the new setpoints. Note however, that the new setpoints are not incorporated in any previously created program pattern.

NOTE

Program setpoints that can be changed during the hold mode are limited only to those of a soak segment (i.e., a segment with invariable program setpoints). It is not possible to change the program setpoints of any ramp segment (a segment whose program setpoints vary with time).



- Bring the Hold-mode operating display into view (appears at power-on).
- Press the **RESET** key twice to display HOLD SP display.
- Press the **ENTER** or **RESET** key to display the required setpoint.
- Press the **ENTER** key once to register the setpoint.

6. Executing "Advance" Function

The following operating procedure advances a segment or segments during program operation.

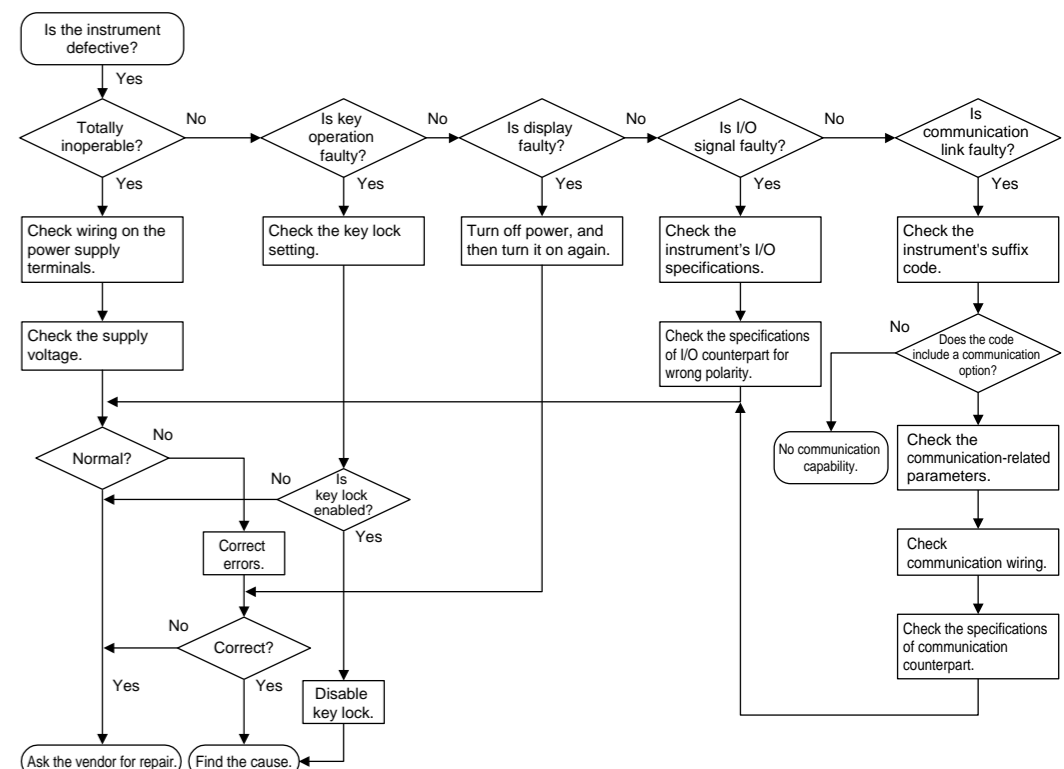
- Bring the operating display into view (appears at power-on).
- Press the **RESET** key for more than 3 seconds to call up the menu "OP.PA".
- Press the **RESET** key twice to display the parameter "ADV".
- Press the **ENTER** key once to display "1".
- Press the **ENTER** key once to register the setpoint.

The controller automatically returns to the display shown at power-on (figure below).

7. Troubleshooting

Troubleshooting Flow

If the operating display does not appear after turning on the controller's power, follow the measures in the procedure below. If a problem appears complicated, contact our sales representative.



IMPORTANT

Take note of the parameter settings when asking the vendor for repair.

Errors at Power On

The following table shows errors that may be detected by the fault diagnosis function when the power is turned on.

Error indication (on PV display unit)	Description of error	PV	Control output	Alarm output	Retransmission output	Communication	Remedy
E000 (E000)	Faulty RAM	None	0% or less or OFF	OFF	0% or less	Stopped	Faulty Contact us for repair.
E001 (E001)	Faulty ROM	0%	Normal action (out of accuracy)	Normal action (out of accuracy)	Normal action (out of accuracy)	Normal action	
E002 (E002)	System data error	0%	Normal action (out of accuracy)	Normal action (out of accuracy)	Normal action (out of accuracy)	Normal action	
PV decimal point blinks.	Faulty calibration value	Normal action (out of accuracy)	Normal action (out of accuracy)	Normal action (out of accuracy)	Normal action (out of accuracy)	Normal action	Check and set the parameters, as they have been set to the limited values.
E400 (E400)	Parameter error	0%	Preset value	OFF	0%	0%	

Possible Errors during Operation

The following shows possible errors occurring during operations.

Error indication (on PV display unit)	Description of error	PV	Control output	Event output	Retransmission output	Communication	Remedy
Displays "RJC" and PV alternately	RJC error	Measured with RJC-OFF	Normal action	Normal action	Normal action	Normal action	Faulty Contact us for repair.
PV value blinks	EEPROM error	Normal action	Normal action	Normal action	Normal action	Normal action	Faulty Contact us for repair.
E300 (E300)	A/D error	105%	Preset value	Normal action	Normal action	Normal action	
BOUt (B.OUT)	PV burnout error	Dependent on the BSL parameter Up-scale: 105% Down-scale: -5%	Preset value	Normal action	Normal action	Normal action	Check wires and sensor.
oBr (OVER) or -oBr (-OVER)	Excessive PV	-5% or 105%	Normal action	Normal action	Normal action	Normal action	Check process.
E200 (E200)	Auto-tuning failure (Time-out)	Normal action	Normal action	Normal action	Normal action	Normal action	Check process. Press any key to erase error indication.
Decimal point on setpoint display blinks.	Faulty communication line	Normal action	Normal action	Normal action	Normal action	Normal action	Check wires and communication parameters, and make resetting. Recovery at normal receipt
All indications off	Runaway (due to defective power or noise)	None	0% or less or OFF	OFF	0% or less	Stopped	Faulty if power off/on does not reset start the unit. Contact us for repair.
All indications off	Power off	None	0%	OFF	0%	Stopped	Check for abnormal power.

If a Power Failure Occurs during Operation

- Momentary power failures shorter than 20 ms
The controller is not affected at all and continues normal operation.
- Power failures of 20 ms or longer
 - Setting parameters that have already been configured retain their settings.
 - Auto-tuning is cancelled.
 - After recovery from a power failure, program operation is stopped. The control output begins with the preset output value.
 - Event output is OFF.

This manual explains how to create programs by citing specific examples. Create user programs by referring to the given programming examples. Programming is not possible when the controller is set in Run mode (PRG). Place the controller in Stop (RESET) mode before you start programming.
Be sure to carry out the settings instructed in **Initial Settings User's Manual** before beginning any of the tasks discussed in this manual.

Contents

1. Overview of Program Patterns
2. Example of Program Pattern Setup Charts
3. Creating Program patterns
4. Changing Program Patterns
5. Lists of Program Parameters
6. Explanation of Program Functions

1. Overview of Program Patterns

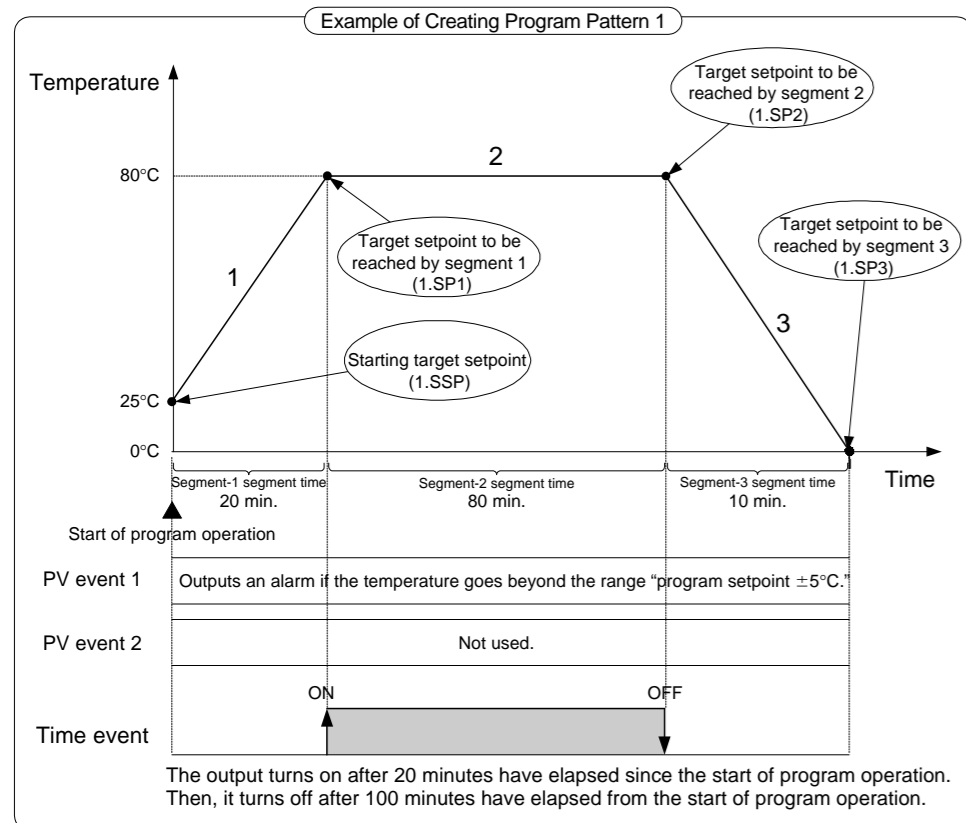
■ Programming Overview

The programming example given here demonstrates how to do the tasks outlined below.

1. Program the controller to start program operation at 25°C and raise the temperature up to 80°C in 20 minutes.
2. When the temperature reaches 80°C, keep it at this level for 80 minutes.
3. Finally, lower the temperature to 0°C in 10 minutes.

Event output

- Set a deviation of 5°C on both the positive and negative sides of a program setpoint to let the controller output an event signal if the temperature goes beyond the deviation range.
- Let the controller output an event signal when the temperature stabilizes to 80°C.



2. Example of Program Pattern Setup Charts

Complete the following setup chart before setting programs in the controller. Filling in the chart makes it easier for you to input program data into the controller. See the back of **Installation User's Manual** for more details. In the following chart, fill in the fields with bold-face borders.

1. Maximum value of PV input range: Setpoint of the "Maximum Value of PV Input Range (RH)" setup parameter
2. Minimum value of PV input range: Setpoint of the "Minimum Value of PV Input Range (RL)" setup parameter
3. PV input unit: Setpoint of the "PV Input Unit (UNIT)" setup parameter
4. Program time unit: Setpoint of the "Program Time Unit (TMU)" setup parameter
5. Segment setting method: Setpoint of the "Segment Setting Method (SEG.T)" setup parameter
6. Starting target setpoint: Setpoint of the "Starting Target Setpoint (SSP)" program parameter
7. Start code: Setpoint of the "Start Code (STC)" program parameter
8. Junction code: Setpoint of the "Junction Code (JC)" program parameter
9. Target setpoint, Segment time, PV events 1 and 2, and Time event: Setpoint of each program parameter
10. Draw the program pattern.

Example of Chart Entries

Program time unit (TMU)	4	Hour, minute	Starting target setpoint (SSP)	8 (25°C)
Segment setting method (SEG.T)	5	Time setting	Start code (STC)	7 0
			Junction code (JC)	8 0

Unit	3	°C
Maximum value of PV input range (RH)	100%	
Minimum value of PV input range (RL)	0%	

Segment No.	1	2	3	4	5	6	7	8	9	10
Target setpoint (SP)	80°C	80°C	0°C	Not used in this example						
Segment time (TM)	20 min	1 hr and 20 min	10 min	Not used in this example						
PV event 1	Deviation upper/lower-limit alarm (setpoint: "7")									
	Deviation bandwidth (setpoint: "5°C")									
PV event 2	Not used in this example									
Time event	On time of time event (EON) The event output turns on 20 minutes after the start of program operation. (setpoint: "20 min")									
	Off time of time event (EOF) The event output turns off 100 minutes after the start of program operation. (setpoint: "1 hr and 40 min")									

3. Creating Program Patterns

The following operating procedure describes an example of creating the program discussed in "1. Overview of Program Patterns."

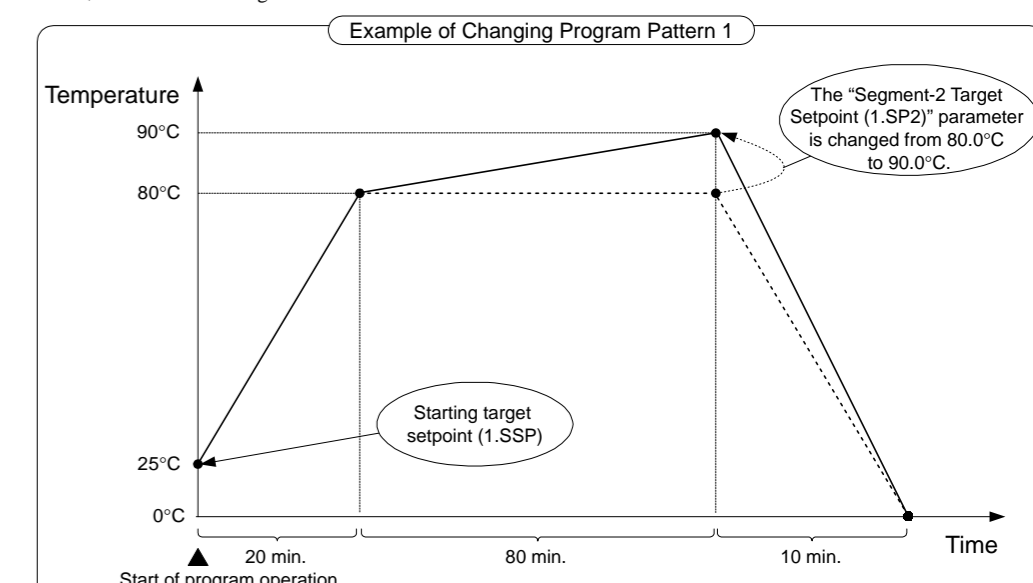
NOTE

Before creating the program, verify the Maximum Value of PV Input Range (RH), Minimum Value of PV Input Range (RL), Program Time Unit (TMU), and Segment Setting Method (SEG.T) parameters. If the setting of the setup parameter "SEG.T" is changed, the program patterns created and stored so far will be all cleared (Initialized) !! Be careful.

The programming example given in this manual includes the following steps.
Steps 4 to 9 configure the PV Event 1 parameter (i.e., a procedure for outputting an alarm if the temperature goes beyond the range "program setpoint ±5°C").
Step 10 configures the PV Event 2 parameter (not configured here).
Steps 11 to 13 configure the On time of Time Event (1.EON) parameter.
Steps 14 to 16 configure the Off Time of Time Event (1.EOF) parameter.
Steps 17 to 19 configure the Starting Target Setpoint (1.SSP) parameter.
Step 20 configures the Start Code (1.STC) parameter (not configured here).
Steps 21 to 23 configure the Segment-1 Target Setpoint (1.SP1) parameter.
Steps 24 to 26 configure the Segment-1 Segment Time (1.TM1) parameter.
Step 27 configures the Segment-2 Target Setpoint (1.SP2) parameter.
Steps 28 to 30 configure the Segment-2 Segment Time (1.TM2) parameter.
Steps 31 to 33 configure the Segment-3 Target Setpoint (1.SP3) parameter.
Steps 34 to 36 configure the Segment-3 Segment Time (1.TM3) parameter.

4. Changing Program Patterns

The following operating procedure describes an example of changing the program pattern created in "3. Creating Program Patterns," as shown in the figure below.



■ Details of the Change

- Before change: Program operation begins with the starting target setpoint (1.SSP).
After change: Program operation begins with the current PV value. → Change the setpoint of the Start Code (1.STC) program parameter to "2".
- Before change: The program parameter Segment-2 Target (1.SP2) was set to "80.0°C".
After change: The Segment-2 Target Setpoint (1.SP2) program parameter is set to "90.0°C". → Change the Segment-2 Target Setpoint (1.SP2) program parameter to "90.0°C".

5. Lists of Program Parameters

● Program-1 Parameters

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
1AL1 (1.AL1)	PV event-1 type	OFF, 1 to 10 1: PV high limit (energized, no stand-by action) 2: PV low limit (energized, no stand-by action) 3: Deviation high limit (energized, no stand-by action) 4: Deviation low limit (energized, no stand-by action) 5: Deviation high limit (de-energized, no stand-by action) 6: Deviation low limit (de-energized, no stand-by action) 7: Deviation high and low limits (energized, no stand-by action) 8: Deviation within high and low limits (energized, no stand-by action) 9: PV high limit (de-energized, no stand-by action) 10: PV low limit (de-energized, no stand-by action)	OFF		
1A1 (1.A1)	PV event-1 setpoint	PV alarm: -100.0 to 100.0% of PV input range Deviation alarm: -100.0 to 100.0% of PV input range span Use the "HY1" setup parameter to set the hysteresis of PV event 1.	PV high limit: 0.0% of PV input range Deviation alarm: 0.0% of PV input range span. Other PV alarms: 0.0% of PV input range.		
1AL2 (1.AL2)	PV event-2 type	OFF, 1 to 10 1: PV high limit (energized, no stand-by action) 2: PV low limit (energized, no stand-by action) 3: Deviation high limit (energized, no stand-by action) 4: Deviation low limit (energized, no stand-by action) 5: Deviation high limit (de-energized, no stand-by action) 6: Deviation low limit (de-energized, no stand-by action) 7: Deviation high and low limits (energized, no stand-by action) 8: Deviation within high and low limits (energized, no stand-by action) 9: PV high limit (de-energized, no stand-by action) 10: PV low limit (de-energized, no stand-by action)	OFF		Ref.3.4(5)
1A2 (1.A2)	PV event-2 setpoint	PV alarm: -100.0 to 100.0% of PV input range Deviation alarm: -100.0 to 100.0% of PV input range span Use the "HY2" setup parameter to set the hysteresis of PV event 2.	PV high limit: 0.0% of PV input range Deviation alarm: 0.0% of PV input range span. Other PV alarms: 0.0% of PV input range.		
1Eon (1.EON)	On time of Time Event	OFF, 0.00 to 99.99 (hour and minute or minute and second) Use the TMU setup parameter to set the time unit. The time unit is the same as that of the program.	OFF		
1EoF (1.EOF)	Off time of Time Event	OFF, 0.00 to 99.99 (hour and minute or minute and second) Use the TMU setup parameter to set the time unit. The time unit is the same as that of the program.	OFF		Ref.3.4(6)
1SSP (1.SSP)	Starting target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
1STC (1.STC)	Start code	0: Operation begins with the starting target setpoint (1.SSP). 1: Ramp-prioritized PV start 2: Time-prioritized PV start	0		Ref.5.2(1)
1SP1 (1.SP1)	Segment-1 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
1TM1 (1.TM1)	Segment-1 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min) Use the TMU setup parameter to set the time unit. The "hour and minute" option in ramp setting means "per hour" and the "minute and second" option means "per minute."	OFF		
1SP2 (1.SP2)	Segment-2 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
1TM2 (1.TM2)	Segment-2 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
1SP3 (1.SP3)	Segment-3 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
1TM3 (1.TM3)	Segment-3 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
1SP4 (1.SP4)	Segment-4 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
1TM4 (1.TM4)	Segment-4 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
1SP5 (1.SP5)	Segment-5 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
1TM5 (1.TM5)	Segment-5 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		Ref.5.1(1)
1SP6 (1.SP6)	Segment-6 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
1TM6 (1.TM6)	Segment-6 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
1SP7 (1.SP7)	Segment-7 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
1TM7 (1.TM7)	Segment-7 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
1SP8 (1.SP8)	Segment-8 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
1TM8 (1.TM8)	Segment-8 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
1SP9 (1.SP9)	Segment-9 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
1TM9 (1.TM9)	Segment-9 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
1SPA (1.SPA)	Segment-10 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
1TMA (1.TMA)	Segment-10 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
1JC (1.JC)	Junction code	0: End of resetting 1: End of hold 2: Pattern 1 startup 3: Pattern 2 startup	0		Ref.5.2(3)

● Program-2 Parameters

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
2AL1 (2.AL1)	PV event-1 type	OFF, 1 to 10 1: PV high limit (energized, no stand-by action) 2: PV low limit (energized, no stand-by action) 3: Deviation high limit (energized, no stand-by action) 4: Deviation low limit (energized, no stand-by action) 5: Deviation high limit (de-energized, no stand-by action) 6: Deviation low limit (de-energized, no stand-by action) 7: Deviation high and low limits (energized, no stand-by action) 8: Deviation within high and low limits (energized, no stand-by action) 9: PV high limit (de-energized, no stand-by action) 10: PV low limit (de-energized, no stand-by action)	OFF		
2A1 (2.A1)	PV event-1 setpoint	PV alarm: -100.0 to 100.0% of PV input range Deviation alarm: -100.0 to 100.0% of PV input range span Use the "HY1" setup parameter to set the hysteresis of PV event 1.	PV high limit: 0.0% of PV input range Deviation alarm: 0.0% of PV input range span. Other PV alarms: 0.0% of PV input range.		
2AL2 (2.AL2)	PV event-2 type	OFF, 1 to 10 1: PV high limit (energized, no stand-by action) 2: PV low limit (energized, no stand-by action) 3: Deviation high limit (energized, no stand-by action) 4: Deviation low limit (energized, no stand-by action) 5: Deviation high limit (de-energized, no stand-by action) 6: Deviation low limit (de-energized, no stand-by action) 7: Deviation high and low limits (energized, no stand-by action) 8: Deviation within high and low limits (energized, no stand-by action) 9: PV high limit (de-energized, no stand-by action) 10: PV low limit (de-energized, no stand-by action)	OFF		Ref.3.4(5)
2A2 (2.A2)	PV event-2 setpoint	PV alarm: -100.0 to 100.0% of PV input range Deviation alarm: -100.0 to 100.0% of PV input range span Use the "HY2" setup parameter to set the hysteresis of PV event 2.	PV high limit: 0.0% of PV input range Deviation alarm: 0.0% of PV input range span. Other PV alarms: 0.0% of PV input range.		
2Eon (2.EON)	On time of Time Event	OFF, 0.00 to 99.99 (hour and minute or minute and second) Use the TMU setup parameter to set the time unit. The time unit is the same as that of the program.	OFF		
2EoF (2.EOF)	Off time of Time Event	OFF, 0.00 to 99.99 (hour and minute or minute and second) Use the TMU setup parameter to set the time unit. The time unit is the same as that of the program.	OFF		Ref.3.4(6)
2SSP (2.SSP)	Starting target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
2STC (2.STC)	Start code	0: Operation begins with the starting target setpoint (2.SSP). 1: Ramp-prioritized PV start 2: Time-prioritized PV start	0		Ref.5.2(1)
2SP1 (2.SP1)	Segment-1 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
2TM1 (2.TM1)	Segment-1 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min) Use the TMU setup parameter to set the time unit. The "hour and minute" option in ramp setting means "per hour" and the "minute and second" option means "per minute."	OFF		
2SP2 (2.SP2)	Segment-2 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
2TM2 (2.TM2)	Segment-2 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
2SP3 (2.SP3)	Segment-3 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
2TM3 (2.TM3)	Segment-3 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
2SP4 (2.SP4)	Segment-4 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
2TM4 (2.TM4)	Segment-4 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
2SP5 (2.SP5)	Segment-5 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
2TM5 (2.TM5)	Segment-5 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		Ref.5.1(1)
2SP6 (2.SP6)	Segment-6 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
2TM6 (2.TM6)	Segment-6 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
2SP7 (2.SP7)	Segment-7 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
2TM7 (2.TM7)	Segment-7 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
2SP8 (2.SP8)	Segment-8 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
2TM8 (2.TM8)	Segment-8 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
2SP9 (2.SP9)	Segment-9 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
2TM9 (2.TM9)	Segment-9 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
2SPA (2.SPA)	Segment-10 target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
2TMA (2.TMA)	Segment-10 segment time	OFF, 0.00 to 99.99 (hour and minute or minute and second) Ramp setting: OFF, 0.0 to 100.0% of PV input range span (1 hr or 1 min)	OFF		
2JC (2.JC)	Junction code	0: End of resetting 1: End of hold 2: Pattern 1 startup 3: Pattern 2 startup	0		Ref.5.2(3)

6. Explanation of Program Functions

■ Programming

You can create programs using either method 1 or 2 described below. The controller is factory-set to "method 1". To create programs using method 2, change the setpoint of the SEG.T (Segment Setting Method) setup parameter to "1". Before you begin programming, determine whether your programs are created using the time unit of "hour and minute" or "minute and second." The controller is factory-set to the "hour and minute" time unit. To create programs using the "minute and second" time unit, change the setpoint of the TMU (Time Unit of Program) setup parameter to "1".

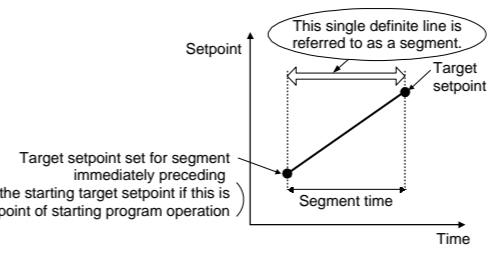
Controller Settings

	Setpoint of SEG.T (Segment Setting Method) Setup Parameter
Time setting (method 1)	0 (factory-set default)
Ramp setting (method 2)	1

Choose the desired method and unit from the two programming methods and time unit options discussed above. Then, create programs according to the chosen options.

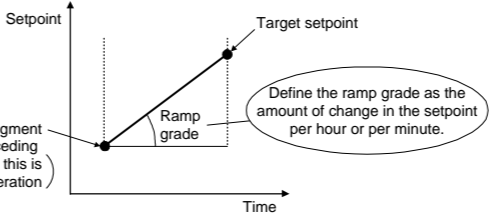
1. Creating programs by setting target setpoint and segment time

As shown in the figure on the right, this method creates programs by setting a segment time and a target setpoint on a segment-by-segment basis.



2. Creating programs by setting target setpoint and ramp

As shown in the figure on the right, this method creates programs by setting a target setpoint and a ramp grade on a segment-by-segment basis. Define the ramp grade as the amount of change in the setpoint per hour or per minute.

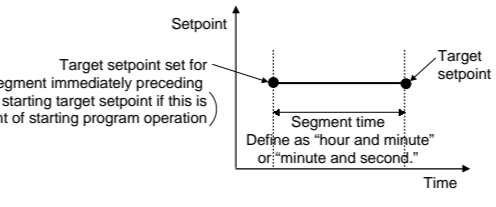


Controller Settings

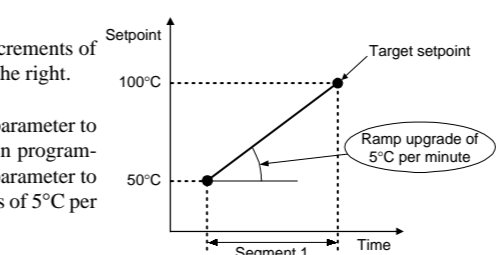
	Setpoint of TMU (Time Unit of Program) Setup Parameter
When changing the setpoint linearly over an hour	0 (factory-set default)
When changing the setpoint linearly over a minute	1

Note: The "Time Unit of Program (TMU)" parameter is the time unit you use when creating programs.

When creating a soak segment during programming, set a time ("hour and minute" or "minute and second") rather than a ramp grade.



For example, configure segment 1 so the temperature rises in increments of 5°C per minute from 50°C to 100°C, as shown in the figure on the right.



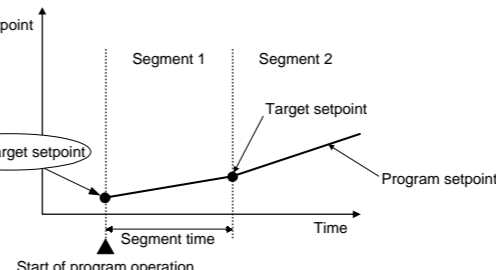
To change the temperature linearly over a minute, set the TMU parameter to "1" (minute and second) before you begin programming. When programming the controller, set the Segment-1 Segment Time (1.TM1) parameter to 5". This allows the controller to raise the setpoint in increments of 5°C per minute during the interval of segment 1.

■ Controller Behavior at the Start of Program Operation

You can determine how the controller should behave at the start of program operation.

1. Letting the controller run from a starting target setpoint

A starting target setpoint refers to a setpoint from which program operation begins. The controller operates in such a manner that the setpoint changes to the target setpoint over the segment time set for segment 1, irrespective of what the PV value is.



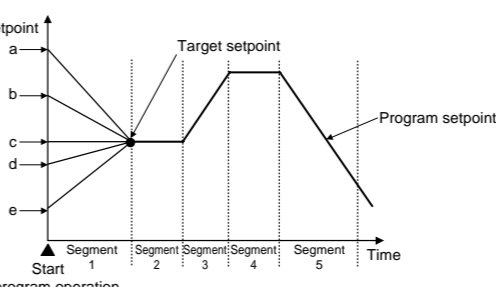
Controller Settings

Set the STC (Start Code) program parameter to "0".

2. Letting the controller start from the current PV and run according to time settings defined for segment 1

This method is not available if the SEG.T (Segment Setting Method) parameter is set to "ramp setting."

Starting Point of Operation	Controller Behavior
a	Begins to run from point a according to the time setting defined for segment 1.
b	Begins to run from point b according to the time setting defined for segment 1.
c	Begins to run from point c according to the time setting defined for segment 1.
d	Begins to run from point d according to the time setting defined for segment 1.
e	Begins to run from point e according to the time setting defined for segment 1.

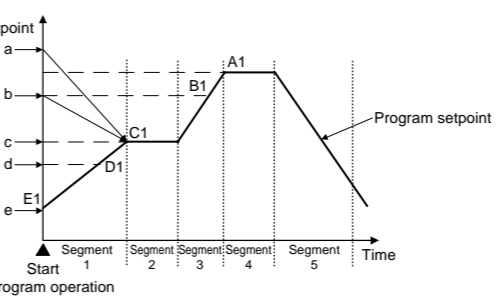


Controller Settings

Set the STC (Start Code) program parameter to "2".

3. Letting the controller start from the current PV and run according to ramp settings defined for segment 1.

Starting Point of Operation	Controller Behavior
a	Begins to run from point C1 (ignores the time setting defined for segment 1).
b	Begins to run from point C1 (ignores the time setting defined for segment 1).
c	Begins to run from point C1 (ignores the time setting defined for segment 1).
d	Begins to run from point D1 according to the preset ramp setting (the time setting defined for segment 1 is reduced).
e	Begins to run from point E1 according to the preset ramp setting.



Controller Settings

Set the STC (Start Code) program parameter to "1".

■ Program-based Selection of PID Constants

See "■ PID Switching (Zone PID)" in the back of **Parameters User's Manual**.

■ Program Repetition

Set a program you want to run repetitively in the Junction Code parameter of a program pattern for which the controller is operated.

For example, if you want to run program pattern 1 repetitively, set the Junction Code parameter to "2". This lets the controller repeat program pattern 1 indefinitely.

Controller Settings

	Setpoint of JC (Junction Code) Program Parameter
Repetition of program pattern 1	Set the parameter Program Pattern-1 Junction Code (1.JC) to "2".
Repetition of program pattern 2	Set the parameter Program Pattern-2 Junction Code (2.JC) to "3".

■ Program Linking

Use this function to append program pattern 2 to program pattern 1 so the controller runs according to the resulting single program pattern. You can also append program pattern 2 to program pattern 1.

Precautions when Linking Programs

There may be a case that a difference exists between the target setpoint defined for the final segment of a program pattern to be run first and the starting target setpoint of a program pattern to be combined with. If this is the case, a deviation may occur and therefore a derivative action may take place, causing the control output to travel up to 100% or down to 0% and stay at this point.

If program linking is assumed, care must be taken to prevent any significant deviation from arising between the setpoints to be linked when creating programs.

Controller Settings

	Setpoint of JC (Junction Code) Program Parameter
To append program pattern 2 to program pattern 1	Set the parameter Program Pattern-1 Junction Code (1.JC) to "3".
To append program pattern 1 to program pattern 2	Set the parameter Program Pattern-2 Junction Code (2.JC) to "2".

■ Retaining the End-of-Program State (End of Hold)

This function keeps the controller in the same state as when the program operation was completed. When in hold operation, the controller retains its states of control output and event output. To cancel hold operation, use either key operation or external contact input. When the hold operation is cancelled, the control output is set to 0% or OFF, and the event output is set to OFF.

To retain the end-of-program state, set a Junction Code program parameter to "1". For example, if you want the controller to run according to program pattern 1 and retain the same state as when the program ended, set the Program Pattern-1 Junction Code (1.JC) parameter to "1".

Controller Settings

	Setpoint of JC (Junction Code) Program Parameter
To quit hold operation in program pattern 1	Set the parameter Program Pattern-1 Junction Code (1.JC) to "1".
To quit hold operation in program pattern 2	Set the parameter Program Pattern-2 Junction Code (2.JC) to "1".

■ Suspending the Progress of a Program (Wait Function)

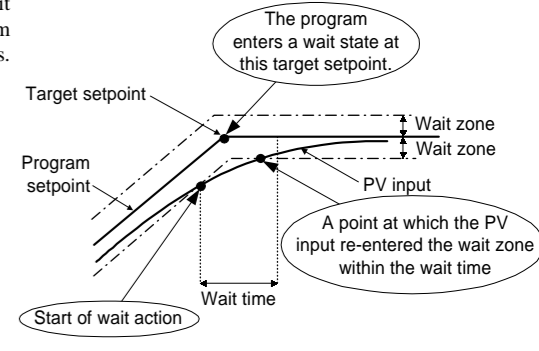
When a running program moves from one segment to another, the wait function places the program in a wait (stand-by) state, by using a wait zone and a wait time, until any deviation is cancelled. The wait function works only when the program moves from a ramp segment (either upgrade or downgrade) to a soak segment (where the setpoint is kept constant).

A wait zone is a deviation bandwidth from which the degree of PV input tracking is judged. A wait time is the length of time that elapses until the PV input enters the wait zone. The program progresses if the PV input fails to re-enter the wait zone within the wait time.

When the program is in the wait state, the time settings of Segment Time and Time Event parameters temporarily cease to be passed. At this point, the output based on the Time Event parameter is retained.

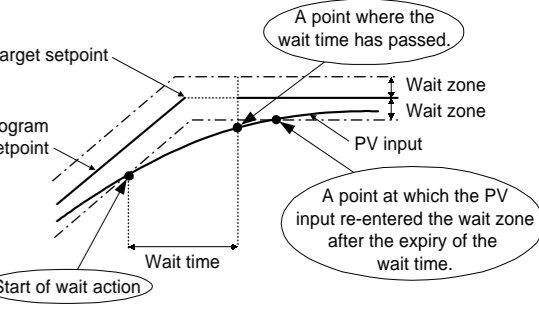
● If the PV input reaches the wait zone before the wait time expires

If the PV input re-enters the wait zone after the start of wait action and before the expiry of the wait time, the program changes from a wait state to a run state and begins to progress.



● If the PV input reaches the wait zone after the wait time expires

If the PV input re-enters the wait zone after the start of wait action and after the expiry of the wait time, the program changes from a wait state to a run state at the point where the wait time has passed, and begins to progress.



2. Lists of Parameters

* Parameters relating to PV or program setpoints should all be set in real numbers. For example, use temperature values to define program setpoints and PV event setpoints for temperature input.

Operating Parameters

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
LL (LL)	LL communication interface selection	OFF: Communication is carried out via the RS485 communication terminals. ON: Communication is carried out via the light-loader adapter.	with communication:OFF without communication:ON	—	—
Adv (ADV)	Advance of segment	This parameter appears during program operation. 0: OFF 1: Execute "Advance" (segments are skipped) These options appear during program operation.	0	—	Ref.5.2(7)
Hold (HOLD)	Hold of program operation	This parameter appears during program operation. 0: OFF 1: Pause (Hold) These options appear during program operation.	0	—	Ref.5.2(3) Ref.5.2(5)
AT (AT)	Auto-tuning	OFF: No auto-tuning 1: Auto-tuning for PID group 1 2: Auto-tuning for PID group 2 3: Auto-tuning for PID group 3 4: Auto-tuning for PID group 4 AUTO Performs auto-tuning to all groups 1 to 4.	OFF	—	—
SC (SC)	"Super" function	OFF: Disable 1: Overshoot suppressing function Suppresses overshoots generated by abrupt changes in the target setpoint or by disturbances. 2: Hunting suppressing function (Stable mode) Suitable to stabilize the state of control when the load varies greatly, or the target setpoint is changed. Enables to answer the wider characteristic changes compared with Response mode. 3: Hunting suppressing function (Response mode) Enables quick follow-up and short converging time of PV for the changed target setpoint. Note: Use "SUPER" function (SC) 2 or 3 in PID control or PI control. "SUPER" function 2 or 3 is not available in the following control: 1) ON/OFF control 2) P control (control for proportional band only) 3) PD control (control for proportional band and derivative item only) Do not use hunting suppressing function when control processes with response such as flow or pressure control.	OFF	—	Ref.2.1(5) Ref.2.1(6)
PI d (PID)	PID parameter display number	MENU Move to FL parameter display 1Gr to 4Gr: Display of each PID parameter	MENU	—	Ref.5.1(2)
FL (FL)	PV input filter	OFF, 1 to 120 second Used when the PV input fluctuates.	OFF	—	Ref.1.1(1)
bS (BS)	PV input bias	-100.0% to 100.0% of PV input range span Used to correct the PV input range.	0.0% of PV input range span	—	Ref.1.1(1)
oh (OH)	Output high limit	-5.0 to 105.0% (OL < OH)	100%	—	Ref.2.1(3)
ol (OL)	Output low limit	-5.0 to 105.0% (OL < OH)	0.0%	—	Ref.2.1(3)
H (H)	ON/OFF control hysteresis	In/ON/OFF control: 0.0 to 100.0% of PV input range span ON/OFF control: 0.5% of PV input range span	0	—	—
DR (DR)	Direct/reverse action switching	0: reverse action, 1: direct action 	0	—	Ref.2.1(1)
WIT.2 (WIT.2)	Wait zone	OFF, 1.0 to 10.0% of PV input range span	OFF	—	Ref.5.2(4)
WIT.1 (WIT.1)	Wait time	0.00 to 99.59 ("hour and minute" or "minute and second") The unit is the same as that set in the Time Unit of Program (TMU) parameter.	0.00	—	Ref.5.2(4)

PID-related Parameters

The following parameters are displayed when "1Gr" is set to PID parameter display number (PID). To set PID corresponding to target setpoint 2 to 4, set "2Gr", "3Gr", or "4Gr" to PID. The relevant parameters will then be displayed.

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
1.P (1.P)	Proportional band	0.1 to 999.9%	5.0%	—	—
1.I (1.I)	Integral time	OFF, 1 to 6000 second	240 second	—	—
1.D (1.D)	Derivative time	OFF, 1 to 6000 second	60 second	—	—
1.MR (1.MR)	Manual reset (enabled when integral time "1.I" is OFF) The manual reset value equals the output value when PV = SP is true. For example, if the manual reset value is 50%, the output value is 50% when PV = SP becomes true.	-5.0 to 105.0%	50.0%	—	—
1.RP (1.RP)	Zone PID reference point-1	0 to 100.0% of PV input range. Note that 1.RP = 2.RP.	100% value of PV input range	—	Ref.5.1(2)

Refer to the table below for recording setpoints when two sets or more of PID parameters are used.

Parameter	n=2	n=3	n=4
n.P			
n.I			
n.D			
n.MR			
n.RP		None	None

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
rdv (RDV)	Reference deviation	OFF, 0.0 to 100.0% of PV input range span Used to select PID constants according to a deviation from the setpoint. The 4th group of PID constants is used when the controller fails to keep track of the deviation.	OFF	—	—

Setup Parameters

Control Function-related Parameters

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
HY1 (HY1)	PV event-1 hysteresis	0.0 to 100.0% of PV input range span	0.5% of PV input range span	—	Ref.3.4(5)
HY2 (HY2)	PV event-2 hysteresis	0.0 to 100.0% of PV input range span	0.5% of PV input range span	—	Ref.3.4(5)
CT (CT)	Control output cycle time	1 to 1000 second	30 second	—	—
PO (PO)	Preset output	-5.0 to 105.0%. In Stop mode, fixed control output can be generated.	0.0%	—	Ref.2.1(8)

* The "User Setting" column in the table below is provided for the customer to record setpoints.

* The column "Target Item in CD-ROM" in the table below provides references from User's Manual (Reference) (CD-ROM Version) which describes items in more detail and items that are not contained in this manual.

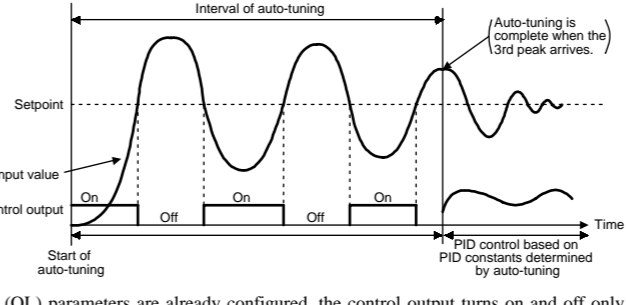
Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
CLnd (CLMD)	PID control mode	0: Standard PID control (with output bump at SP change) 1: Fixed point control (without output bump at SP change) Choose "fixed point control" when controlling pressure or flow rate.	0	—	Ref.2.1(2)
AR (AR)	Anti-reset windup (Excess integration prevention)	AUTO (0), 50.0 to 200.0% Used when the control output travels up to 100% or down to 0% and stays at this point. The larger SP, the sooner PID computation (integral computation) stops.	AUTO	—	Ref.2.1(4)
TMU (TMU)	Program time unit	0: Hour and minute, 1: Minute and second Time unit used when setting a program pattern or a wait time.	0	—	—
SEGT (SEG.T)	Segment setting method	0: Time setting 1: Ramp setting If the setting of the setup parameter "SEG.T" is changed, the program patterns created and stored so far will be all cleared (initialized) !! Be careful.	0	—	Ref.5.1(1)
PSL (P.SL)	Protocol selection	0: PC link communication (with sum check) 1: Ladder communication 2: Coordinated master station 3: MODBUS (ASCII) 4: MODBUS (RTU)	0	—	—
bPS (BPS)	Baud rate	0:600, 1:1200, 2:2400, 3:4800, 4:9600 (bps)	4	—	—
PrI (PRI)	Parity	0: None 1: Even 2: Odd	1	—	Communication function
STP (STP)	Stop bit	1, 2	1	—	Communication function
dLn (DLN)	Data length	7, 8 Fixed at 7, when the P.SL parameter is set to MODBUS (ASCII). Fixed at 8, when the P.SL parameter is set to MODBUS (RTU) or Ladder Communication.	8	—	Communication function
Rdr (ADR)	Address	1 to 99 However, the maximum number of stations connectable is 31.	1	—	Communication function
rPt (RP.T)	Minimum response time	0 to 10 (× 10 ms)	0	—	Communication function
TEST (TEST)	Test function	If this parameter symbol appears, press the SET/ENT key to return to the FUNC menu. Caution: Do not change the setpoint of the TEST parameter, otherwise the indicator will be disabled.	—	—	—

Input/Output-related Parameters

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
IN (IN)	PV input type (PV INPUT terminals)	OFF, 1 to 18, 30, 31, 35 to 37, 40, 41, 50, 51, 55, 56 See Instrument Input Range Codes in Initial Settings User's Manual .	OFF	—	—
UNIT (UNIT)	PV input unit	°C: degree Celsius °F: Fahrenheit (This parameter is not shown for voltage input.)	°C	—	—
rH (RH)	Max. value of PV input range	Set the PV input range, however RL < RH -Temperature input Set the range of temperature that is actually controlled. -Voltage input Set the range of a voltage signal that is applied. The scale across which the voltage signal is actually controlled should be set using the parameters Maximum Value of PV Input Scale (SH) and Minimum Value of PV Input Scale (SL).	—	—	—
rL (RL)	Min. value of PV input range	—	—	—	—
SDP (SDP)	PV input decimal point position (displayed at voltage input)	0 to 3 Set the position of the decimal point of voltage-mode PV input. 0: No decimal place 1: One decimal place 2, 3: Two, three decimal places	1	—	—
SH (SH)	Max. value of PV input scale (displayed at voltage input)	-1999 to 9999, however SL < SH Set the read-out scale of voltage-mode PV input.	100.0	—	—
SL (SL)	Min. value of PV input scale (displayed at voltage input)	—	0.0	—	—
rJC (RJC)	Presence/absence of PV input reference junction compensation	OFF, ON	ON	—	—
bSL (BSL)	Selection of PV input burnout action	OFF 1: Up scale 2: Down scale	1	—	—
OT (OT)	Control output type	0: Time proportional PID relay contact output (terminals ①-②-③) 1: Time proportional PID voltage pulse output (terminals ④-⑤-⑥) 2: Current output (terminals ⑦-⑧) 3: ON/OFF control relay contact output (terminals ①-②-③)	—	—	—
rEt (RET)	Retransmission output type	OFF: Does not work. 1: PV, 2: SP, 3: OUT, 4: Loop power supply for sensor (15 V)	1	—	Ref.2.2(1)
rTH (RTH)	Max. value of retransmission output scale	RET=1, 2: RTH + 1 digit to 100% of PV input range	100% of PV input range	—	Ref.2.2(1)
rTL (RTL)	Min. value of retransmission output scale	RET=1, 2: 0% of PV input range to RTH - 1 digit	0% of PV input range	—	Ref.2.2(1)
dI S (DIS)	DI function selection	OFF: Disables the external contact input. 1: D1: Starts (on)/stops (off) program-1 operation. D2: Starts (on)/stops (off) program-2 operation. 2: D1: Hides (on)/shows (off) the LOCK setup parameter. D2: Unused. 3: D1: Starts (on)/stops (off) program-1 operation. D2: Enables (on)/disables (off) the hold mode of program-1 operation.	OFF	—	Ref.3.1(5)
C.S1 (C.S1)	SELECT display-1 registration	OFF, 201 to 1015 Select the desired parameter from among the operating and setup parameters, then register the number (D register No.) accompanying that parameter. For example, registering "306" for C.S1 allows you to change proportional band (1.P) in operating display. See User's Manual (Reference) (CD-ROM).	OFF	—	Ref.6.1(1)
C.S2 (C.S2)	SELECT display-2 registration	—	—	—	Ref.6.1(1)
C.S3 (C.S3)	SELECT display-3 registration	—	—	—	Ref.6.1(1)
C.S4 (C.S4)	SELECT display-4 registration	—	—	—	Ref.6.1(1)
LOCK (LOCK)	Key lock	OFF: No key lock 1: Change to any parameter prohibited Prohibits any operating parameter or setup parameter from being changed. The setpoint of the LOCK parameter itself can be changed, however. 2: Change to any display of operating parameters prohibited Turns off the display for setting operating parameters, thus prohibiting any change to the parameter settings. (Hold down the SET/ENT key for more than 3 seconds to show the password check display.) 3: Disables the RESET key on the instrument's front panel. 4: Disables the PRG1 key on the instrument's front panel. 5: Disables the PRG2 key on the instrument's front panel. 6: Disables both the PRG1 and PRG2 keys on the instrument's front panel. 7: Prohibits the parameter settings of program pattern 1 from being changed. 8: Prohibits the parameter settings of program pattern 2 from being changed. 9: Prohibits the parameter settings of both program pattern 1 and program pattern 2 from being changed.	OFF	—	Ref.7.1(2)
PwD (PwD)	Password setting	0: Password not set 1 to 9999	0	—	Ref.7.1(1)

Auto-tuning

Auto-tuning is a function with which the controller automatically measures the process characteristics to automatically set the optimum PID constants. This function does not work when the controller is performing on-off control. The UP350 employs the "Limit Cycle Method." As shown in the figure on the right, the controller temporarily changes its control output in a step-waveform manner. Then, it calculates the optimum proportional band (P), integral time (I) and derivative time (D) from the resulting response to set them in their respective parameters. If the Output High Limit (OH) and Output Low Limit (OL) parameters are already configured, the control output turns on and off only between the output's high and low limits during auto-tuning.



When One Group of PID Constants is Used (factory-set default)

Setting of AT Parameter	Auto-tuned Setpoint	Remarks
OFF	-	Auto-tuning is turned off (disabled).
1	The setpoints when auto-tuning is started	Determines the values of 1.P, 1.I and 1.D parameters by auto-tuning.

When Two Groups of PID Constants are Used (See "PID Switching (Zone PID)" below)

Setting of AT Parameter	Auto-tuned Setpoint	Remarks
OFF	-	Auto-tuning is turned off (disabled).
1	The setpoints when auto-tuning is started	Determines the values of 1.P, 1.I and 1.D parameters by auto-tuning.
2	The setpoints when auto-tuning is started	Determines the values of 2.P, 2.I and 2.D parameters by auto-tuning.
AUTO	Median value of each zone width	Determines the values of all PID parameters in use by auto-tuning.

When Three Groups of PID Constants are Used (See "PID Switching (Zone PID)" below)

Setting of AT Parameter	Auto-tuned Setpoint	Remarks
OFF	-	Auto-tuning is turned off (disabled).
1	The setpoints when auto-tuning is started	Determines the values of 1.P, 1.I and 1.D parameters by auto-tuning.
2	The setpoints when auto-tuning is started	Determines the values of 2.P, 2.I and 2.D parameters by auto-tuning.
3	The setpoints when auto-tuning is started	Determines the values of 3.P, 3.I and 3.D parameters by auto-tuning.
AUTO	Median value of each zone width	Determines the values of all PID parameters in use by auto-tuning.

When PID Constants are Selected According to the Deviation (See "PID Switching (Zone PID)" below)

Setting of AT Parameter	Auto-tuned Setpoint	Remarks
4	The setpoints when auto-tuning is started	Determines the values of 4.P, 4.I and 4.D parameters by auto-tuning.

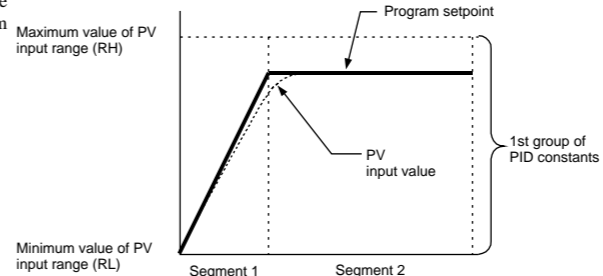
Note: Set the maximum and minimum values, as close as possible to those of the actual range to be controlled, in the Maximum Value of PV Input Range (RH) and Minimum Value of PV Input Range (RL) parameters. Otherwise, the controller may fail to determine the optimum values when auto-tuning is carried out.

PID Switching (Zone PID)

The UP350 carries out control by automatically switching between groups of PID constants according to the temperature zone. You can set a maximum of three temperature zones. When shipped from the factory, the UP350 is configured so that it operates in zone 1 only and using only one group of PID constants.

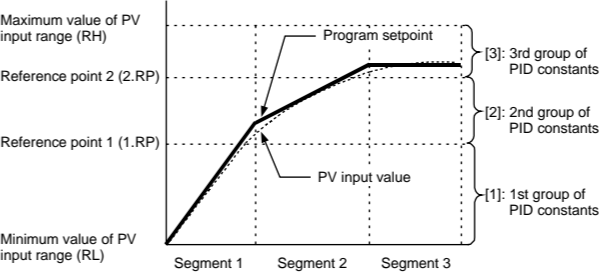
When One Group of PID Constants is Used (factory-set default)

As shown in the figure on the right, the controller uses one group of PID constants over the range from the minimum value to the maximum value of the PV input range.



Selection of PID Constants when the Control Range is Split into Three Zones

As shown in the figure on the right, three zones are set for the controller to automatically switch from one group of PID constants to another. Two zones can also be set for the controller to select between two groups of PID constants.



Controller Settings

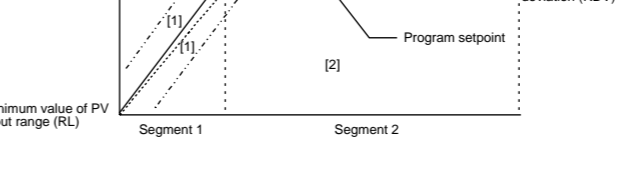
- Splitting the control range into two zones
 - To split the control range into two zones, define reference point 1 (i.e., the 1.RP operating parameter).
 - Define the 1st and 2nd groups of PID constants (i.e., the 1.P, 1.I and 1.D operating parameters for the 1st group and the 2.P, 2.I and 2.D operating parameters for the 2nd group).
- Splitting the control range into three zones
 - To split the control range into three zones, define reference points 1 and 2 (i.e., the 1.RP and 2.RP operating parameters).
 - Define the 1st, 2nd and 3rd groups of PID constants (i.e., the 1.P, 1.I and 1.D operating parameters for the 1st group, the 2.P, 2.I and 2.D operating parameters for the 2nd group and the 3.P, 3.I and 3.D operating parameters for the 3rd group).

Selecting PID Constants According to the Deviation

PID constants can be selected according to the deviation in two ways. One method is to select a group of PID constants only by a deviation from a program setpoint. The other method is to use a reference point, as well as a deviation from a program setpoint, to switch between groups of PID constants. Deviation-based switching has priority over switching based on a reference point.

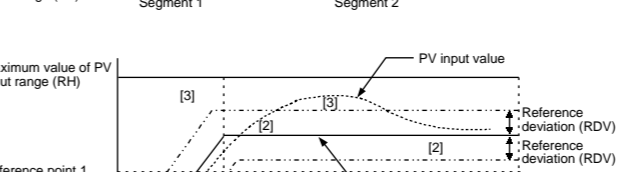
Method 1:

As shown in the figure on the right, the controller selects the 4th group of PID constants if the PV input value goes beyond the given deviation from the program setpoint.



Method 2:

As shown in the figure on the right, the controller selects an appropriate group of PID constants for each zone and, if the PV input value goes beyond the given deviation from the program setpoint, selects the 4th group of PID constants.



- The controller uses the 1st group of PID constants if the PV input value is both within the zone set off by the minimum value of the PV input range and reference point 1 and within the given reference deviation bandwidth.
- The controller uses the 4th group of PID constants if the PV input value is both within the zone set off by the minimum value of the PV input range and reference point 1 and within the given reference deviation bandwidth.

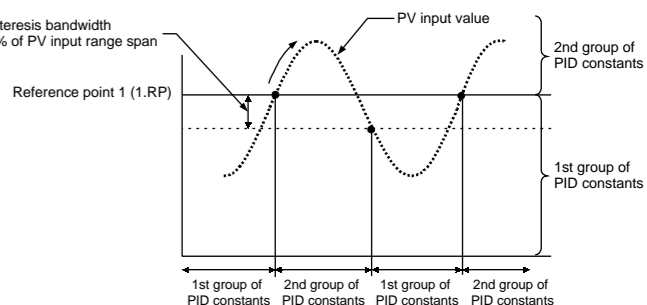
- The controller uses the 2nd group of PID constants if the PV input value is both within the zone set off by reference point 1 and the maximum value of the PV input range and within the given reference deviation bandwidth.
- The controller uses the 4th group of PID constants if the PV input value goes beyond the given reference deviation bandwidth.

Controller Settings

- Splitting the control range into two zones
 - To split the control range into two zones, define reference point 1 (i.e., the 1.RP operating parameter).
 - Define the 1st and 2nd groups of PID constants (i.e., the 1.P, 1.I and 1.D operating parameters for the 1st group and the 2.P, 2.I and 2.D operating parameters for the 2nd group).
 - Define the reference deviation (i.e., the RDV operating parameter).
 - The RDV parameter appears after the 4th group of PID parameters.
- Splitting the control range into three zones
 - To split the control range into three zones, define reference points 1 and 2 (i.e., the 1.RP and 2.RP operating parameters).
 - Define the 1st, 2nd and 3rd groups of PID constants (i.e., the 1.P, 1.I and 1.D operating parameters for the 1st group, the 2.P, 2.I and 2.D operating parameters for the 2nd group and the 3.P, 3.I and 3.D operating parameters for the 3rd group).
 - Define the reference deviation (i.e., the RDV operating parameter).
 - The RDV parameter appears after the 4th group of PID parameters.

Hysteresis for PID switching (if Zone PID is used)

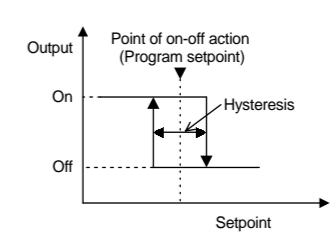
Hysteresis is set for PID switching at reference point 1, as shown in the figure on the right. The hysteresis bandwidth is fixed at 0.5% of the span of the PV input range. Reference point 2 behaves in the same way as reference point 1, though the figure shows reference point 1 only.



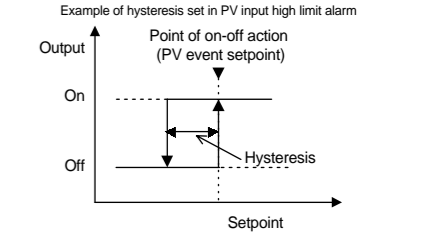
Hysteresis (Setpoints for On-Off Control and PV Event Setpoints)

Hysteresis can be set in on-off control setpoints and PV event setpoints as well. With the hysteresis settings, it is possible to prevent relays from chattering.

When hysteresis is set in an on-off control setpoint



When hysteresis is set in a PV event setpoint



Hysteresis (H): Operating parameter

PV event-1 hysteresis (HY1): Setup parameter
PV event-2 hysteresis (HY2): Setup parameter

Useful Operating Display (SELECT display)

Registering frequently changed parameters in the SELECT display after ordinary operating displays will allow you to change settings easily. A maximum of four ordinary displays can be registered.

